

ERGONOMICS

Michael Patkin FRACS

[mpatkin \[at\] bigpond.net.au](mailto:mpatkin@bigpond.net.au)

mpatkin.org

QEH 13 February 2009

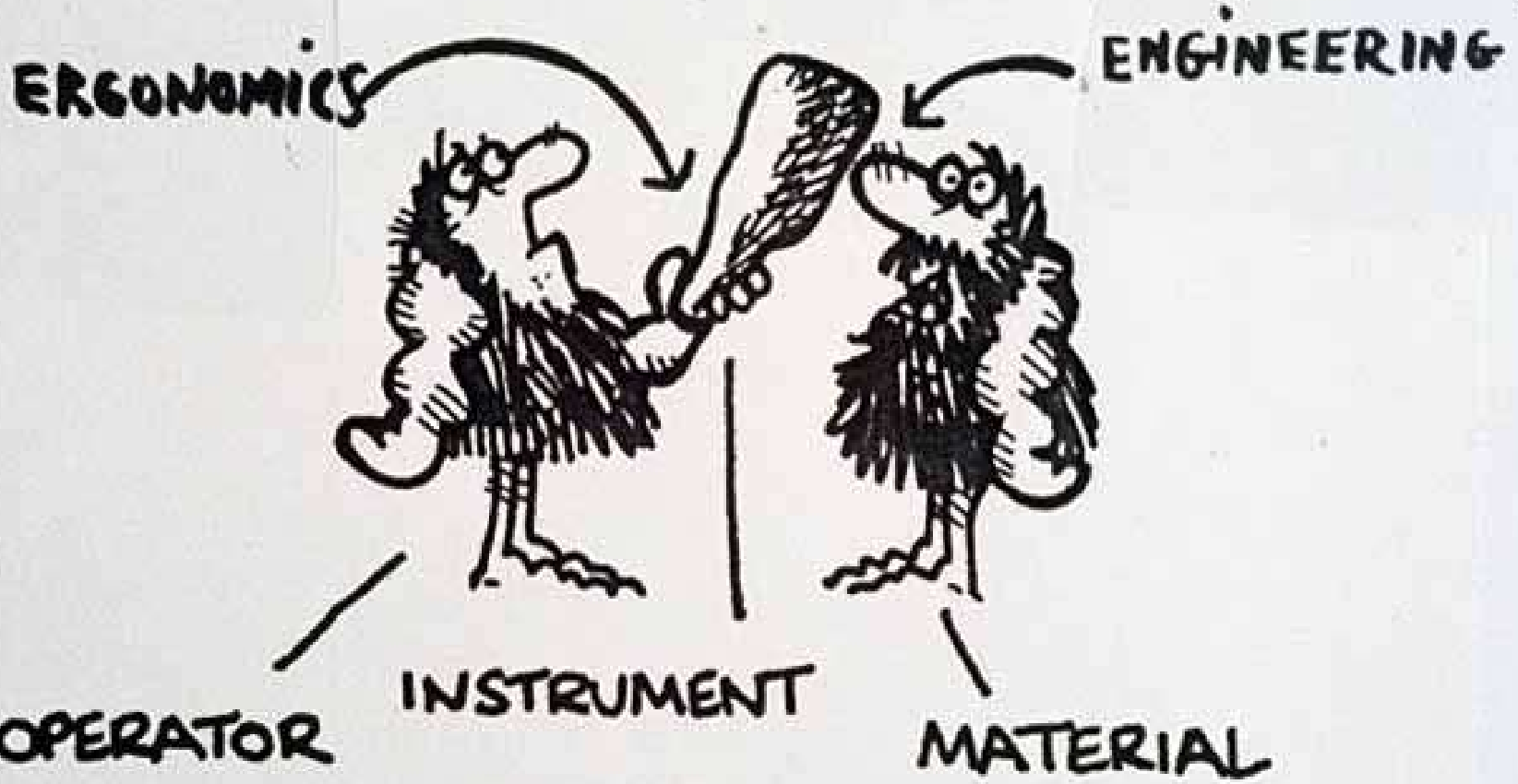
This morning

- Ergonomics
 - What it is
 - What's it useful for
 - Applications to surgery
-

- Heuristics in surgery

Model of a surgeon at work





Ergonomics – definition

Ergonomics – definition

- Scientific study of people at work

Ergonomics – definition

- Scientific study of people at work
- based on
 - anatomy
 - physiology
 - psychology
 - engineering

Ergonomics – definition

- Scientific study of people at work
- based on
anatomy, physiology, psychology, engineering
- combined in a systems approach

Ergonomics – definition

- Scientific study of people at work
- based on
anatomy, physiology, psychology, engineering
- combined in a systems approach

Values!

Ergonomics – definition

- Scientific study of people at work
- based on
 anatomy, physiology, psychology, engineering
- Combined in a systems approach

- with a view to

Improving training

Safety ↑

Productivity ↑

Accuracy ↑

Satisfaction at work ↑

Ergonomics – definition

- Scientific study of people at work
- based on anatomy, physiology, psychology, engineering
- in a systems approach

- With a view to

Training ↑

Safety ↑

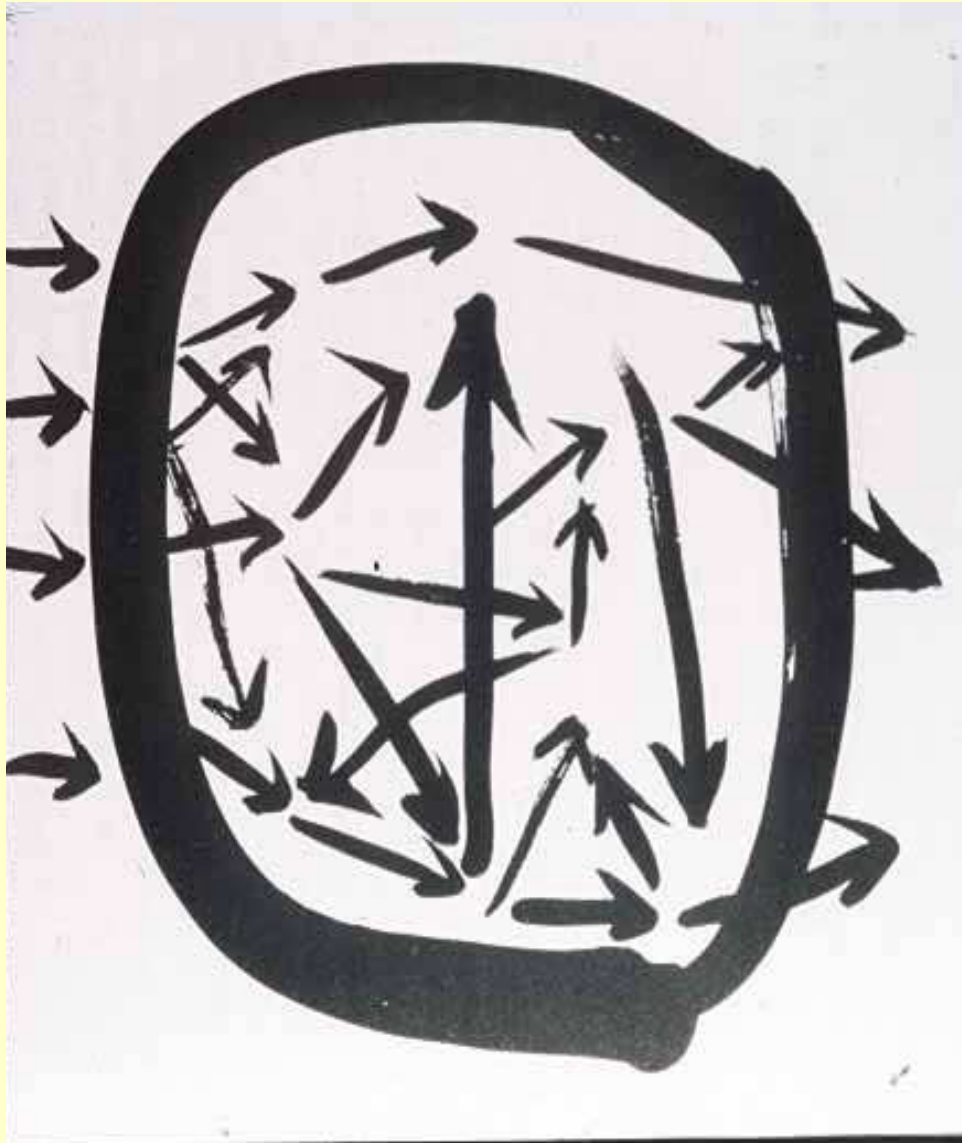
Productivity ↑

Accuracy ↑

Satisfaction at work ↑

All these
can be measured

What is a system?

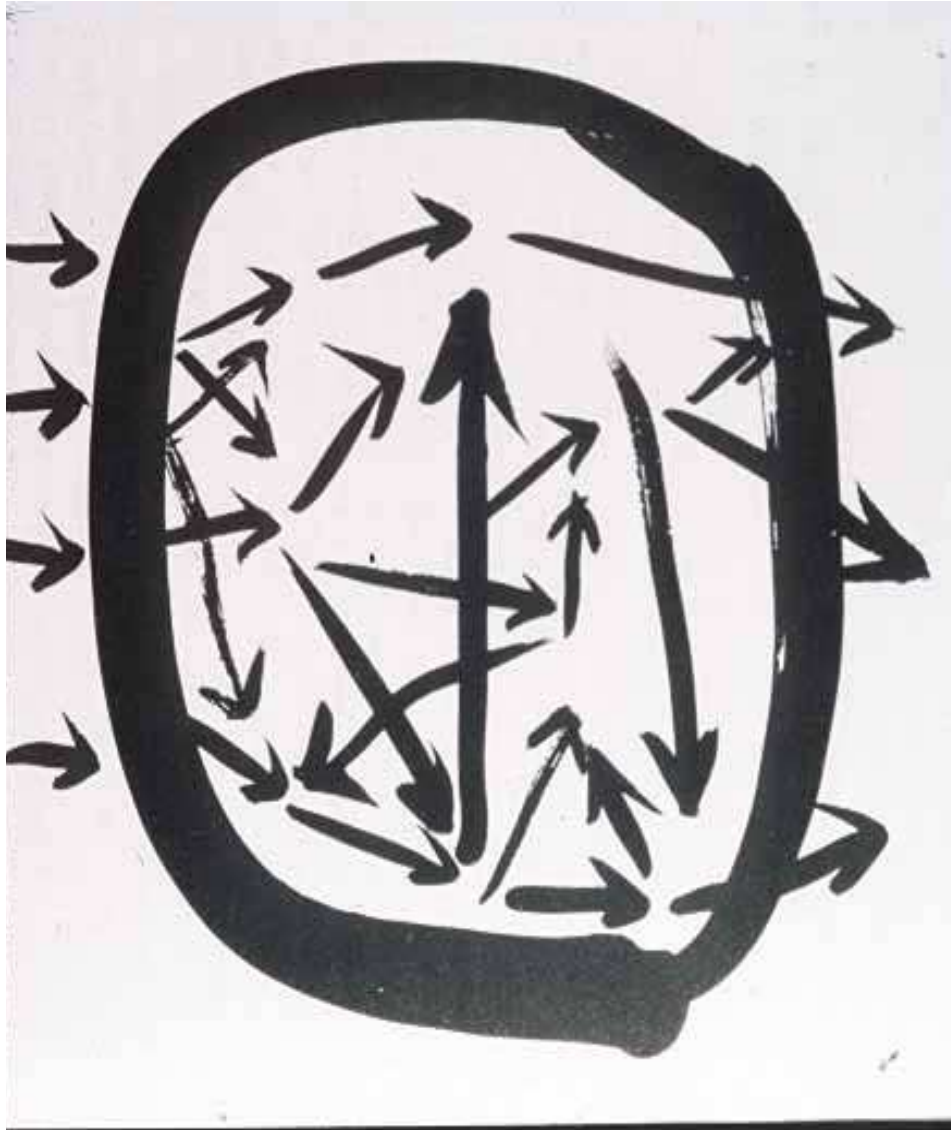


A system:

a set of items, links, and interactions
with inputs, outputs.

whose behaviour as a whole
can not be predicted from
behaviour of its elements or
of groups of elements

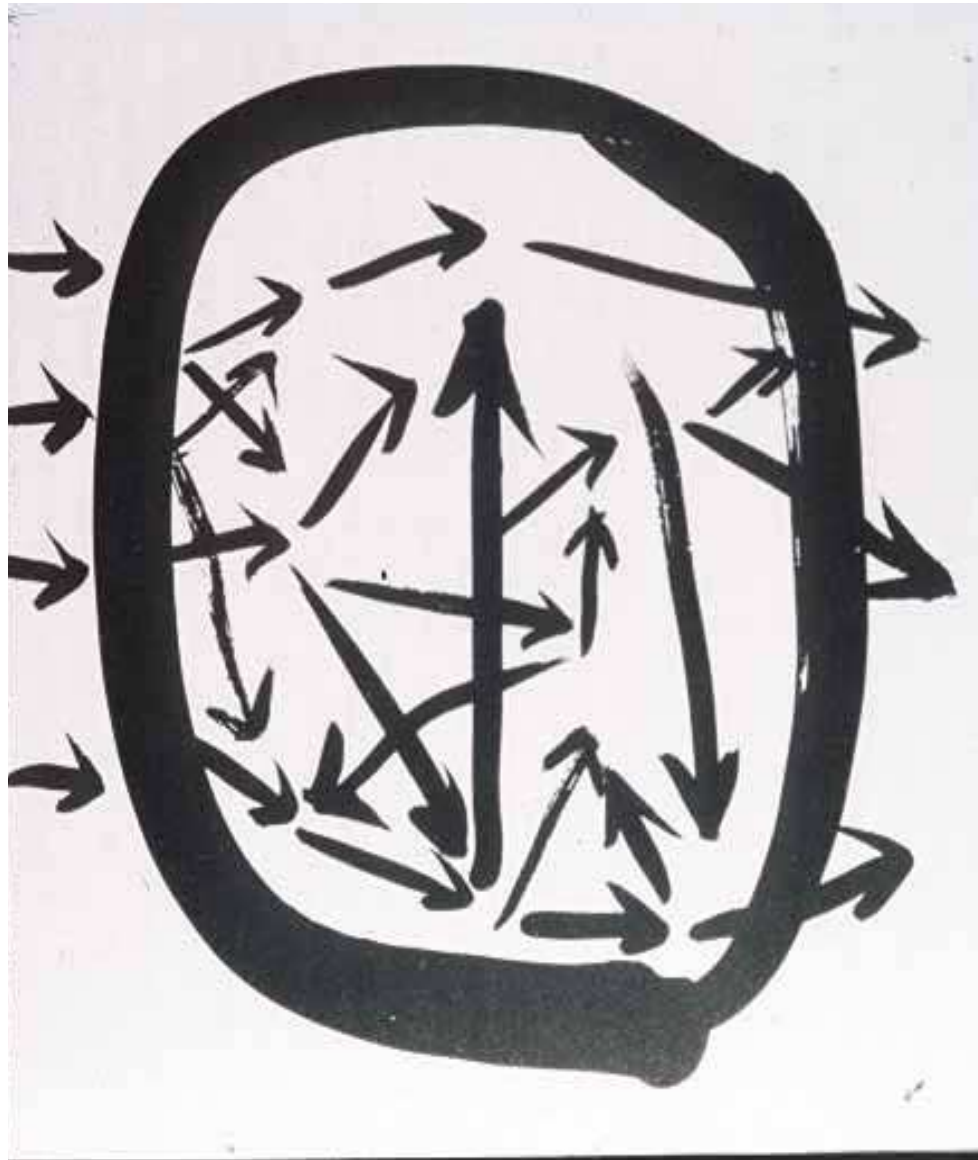
= emergent properties



A system:

emergent properties

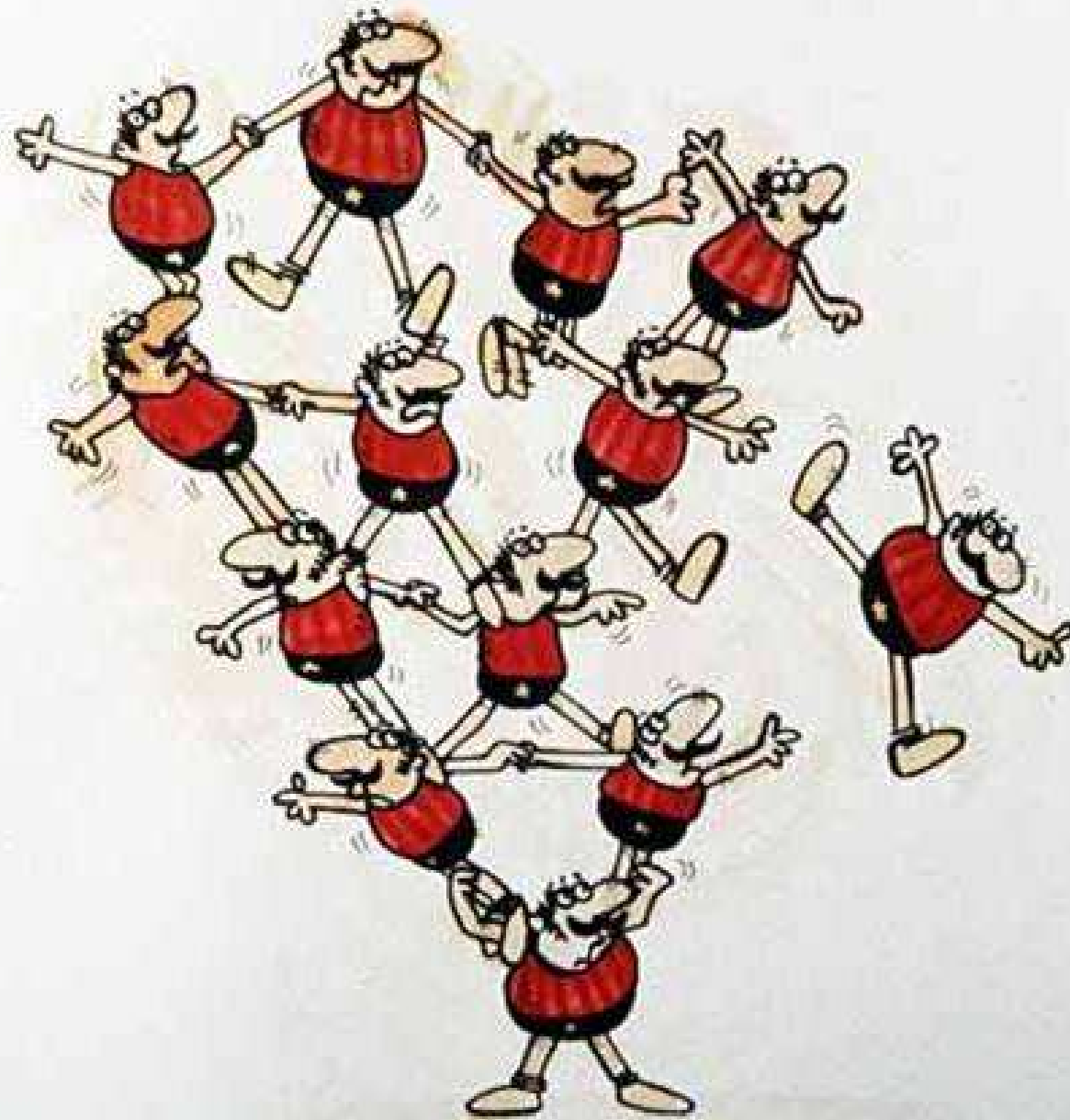
.... “it seemed like
a good idea
at the time”

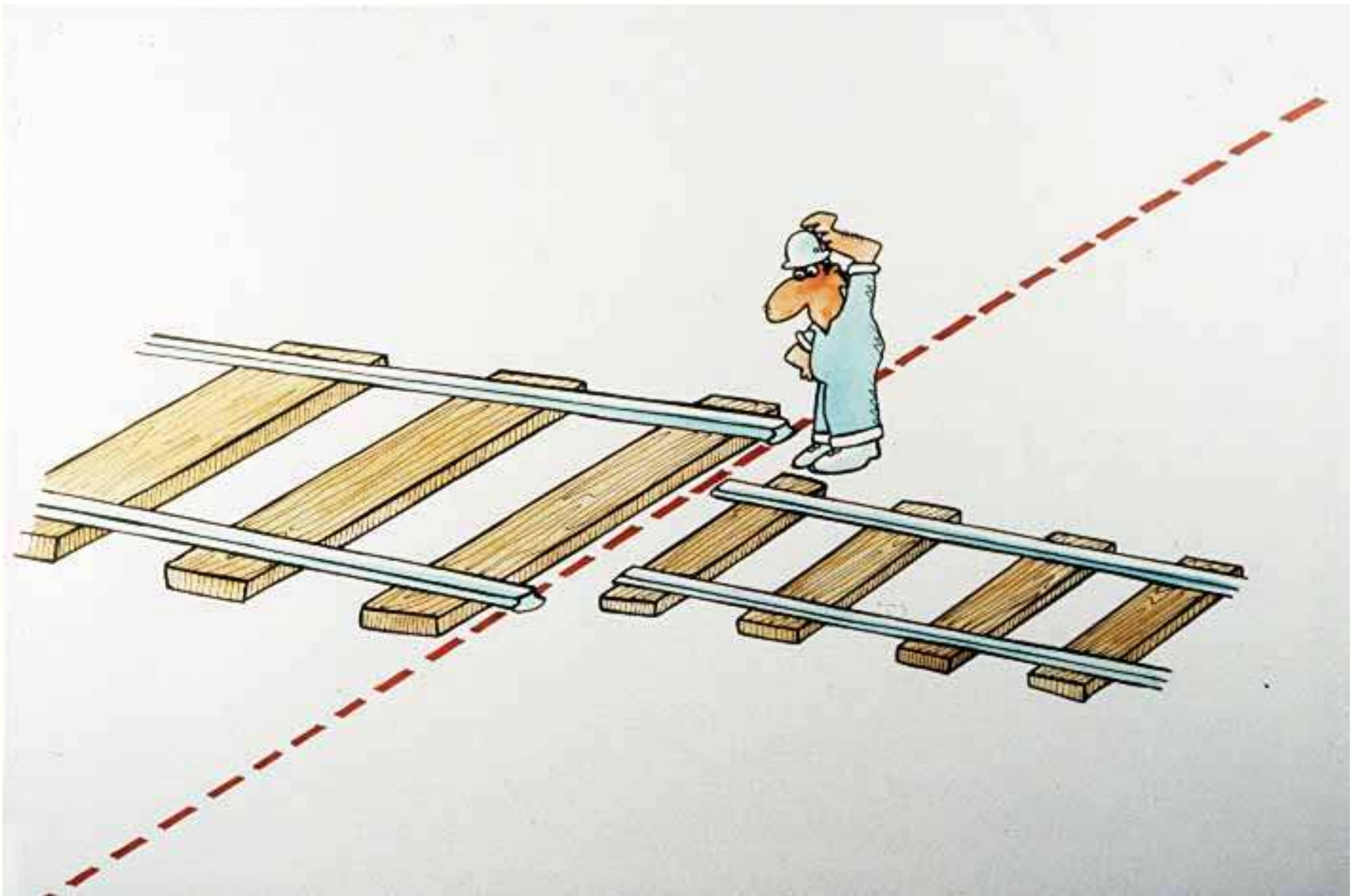


A system:

Also,

stability and
coupling vary





... yet another system problem ...

Ergonomics – history

Ergonomics – context

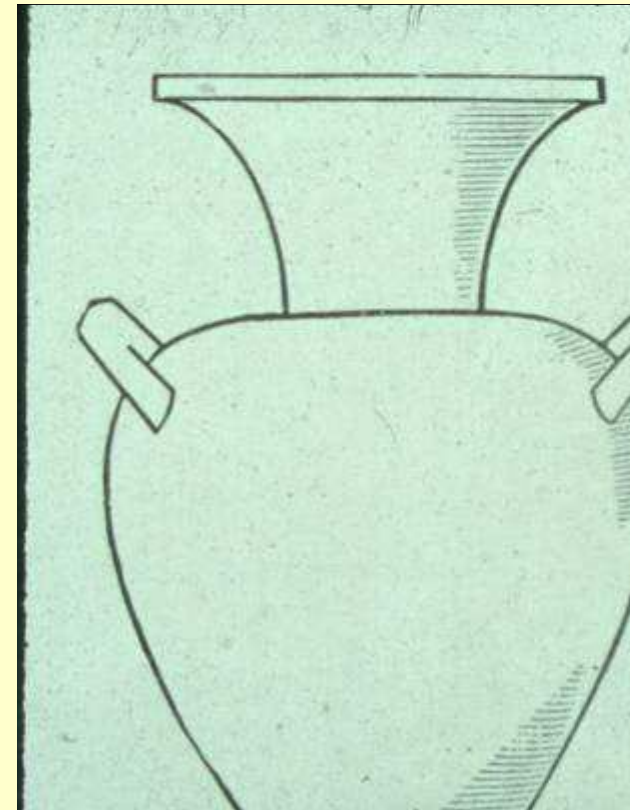
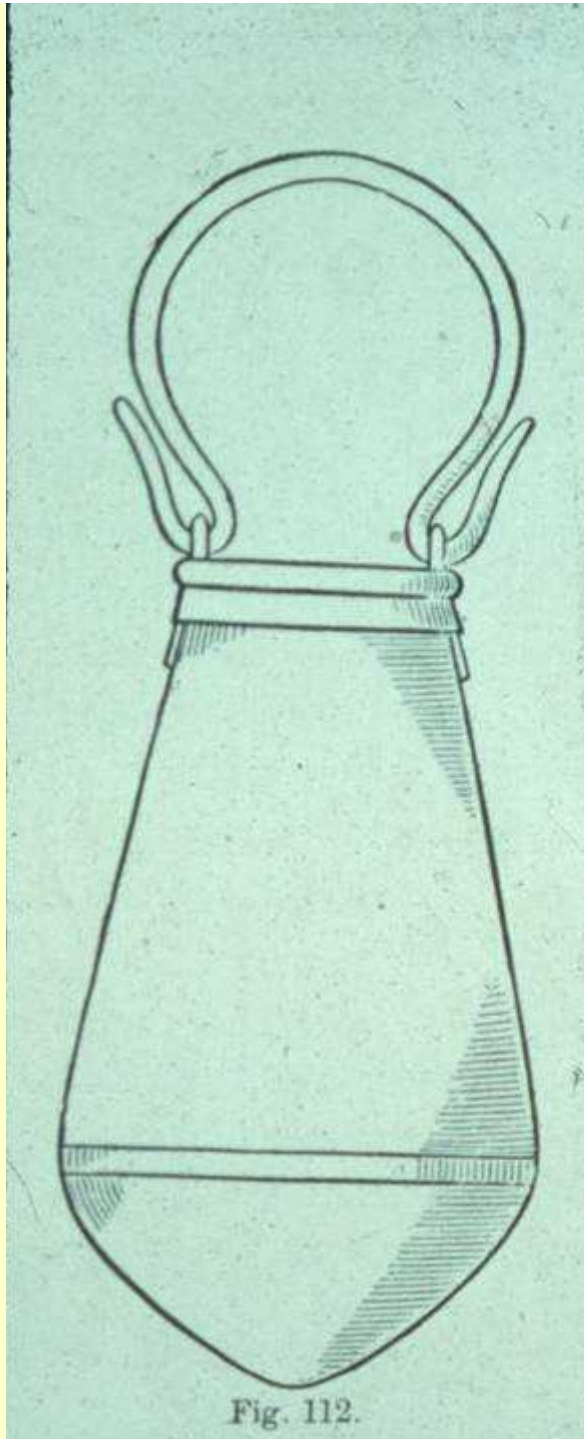
Good managers, engineers and craftspersons have often been intuitive ergonomists

- Ancient Greek and Egyptian water carriers
- Duke of Malborough provided boots for soldiers
- Utson and the Sydney Opera House – poor backstage facilities, poor acoustics, poor car parking

Ancient water carriers –

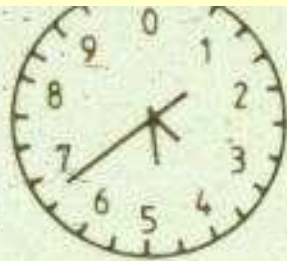
Which was from Greece & which from Egypt?

Why?

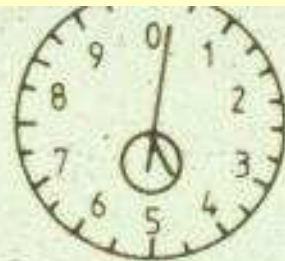


Ergonomics – early history

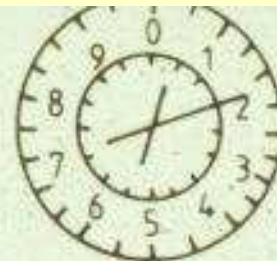
- 1880s – time and motion study
- 1881 – FW Taylor, Bethlehem Steel Works, Pittsburgh – shovelling of coal, loading of trucks
- 1900s – scientific management, Frank Gilbreth (“Cheaper by the Dozen”)
- 1940s – WW2 – eg altimeters in fighter aircraft
- 1950s – aerospace program
- 1960s – factories, product design
- 1970s - occ health & safety, RSI
- 1980s – human-computer interaction, macroergonomics, cognitive ergonomics
- 1990s – James Reason (human error), CRM



A



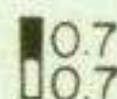
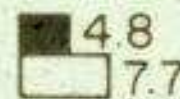
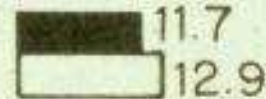
B



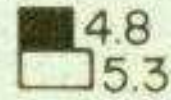
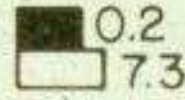
C

D

Percent errors of 1000 feet or more



Interpretation time in seconds

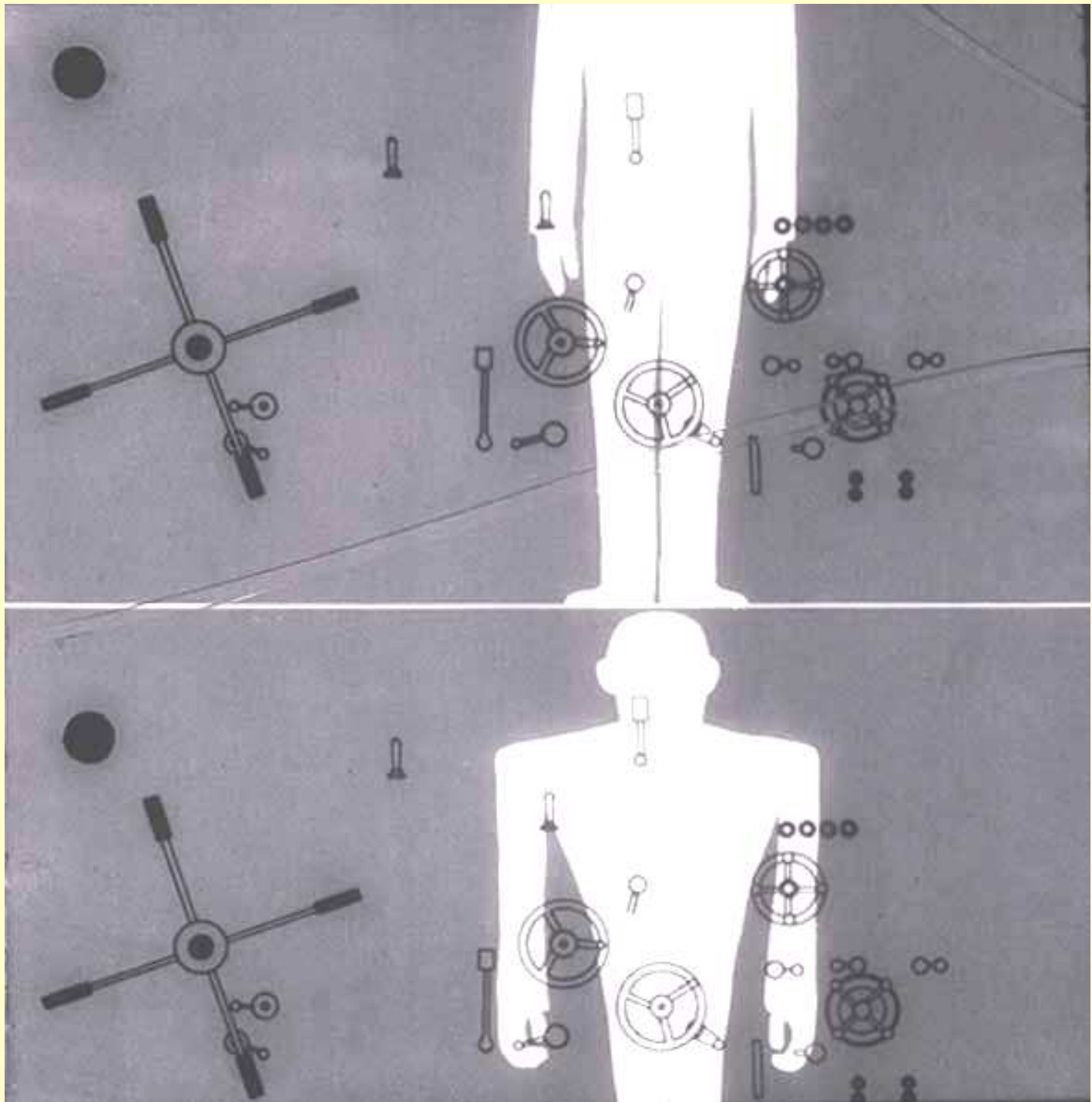


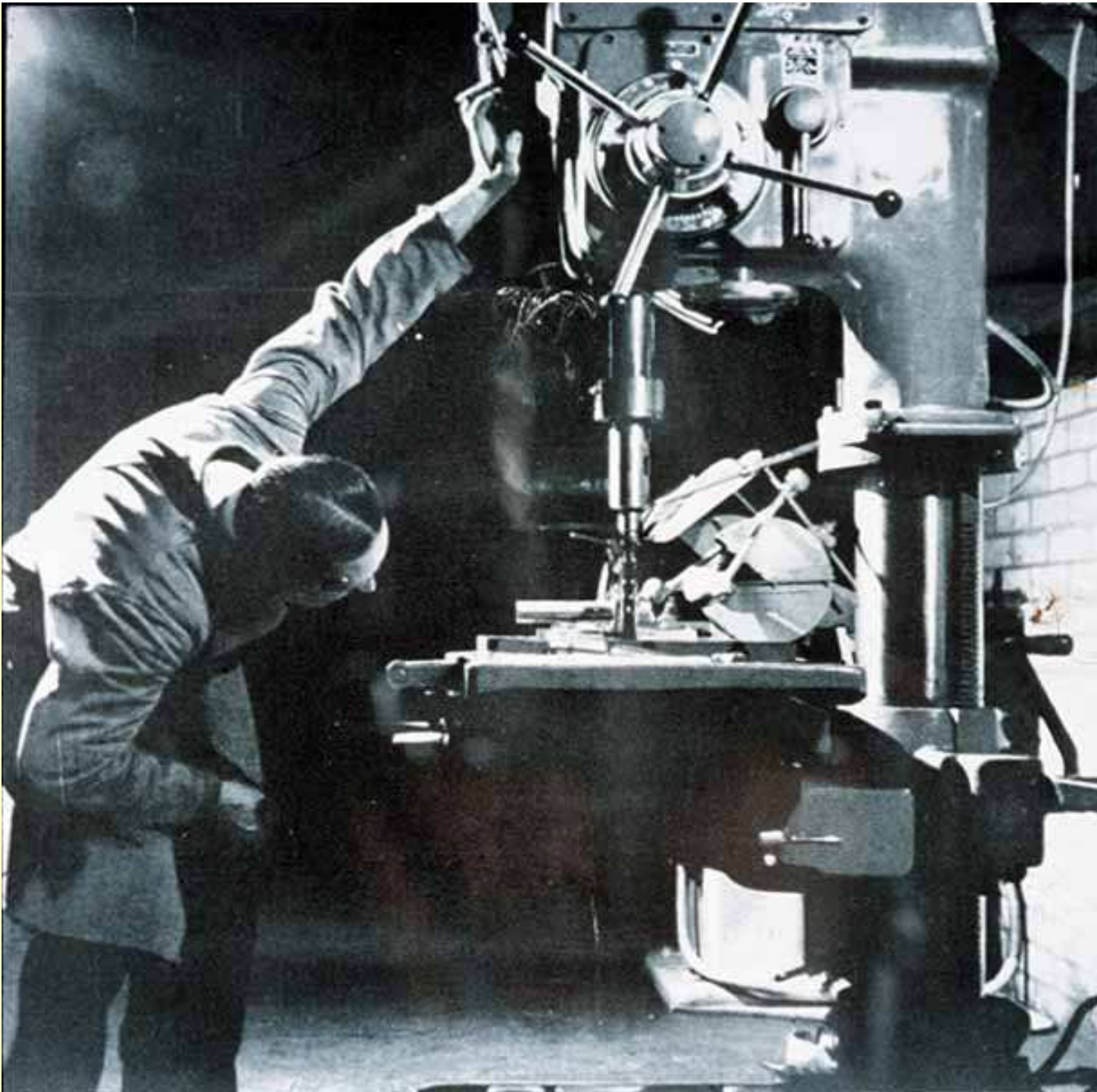


Original

Improved

Other dials and indicators







Karl Storz OR of the future



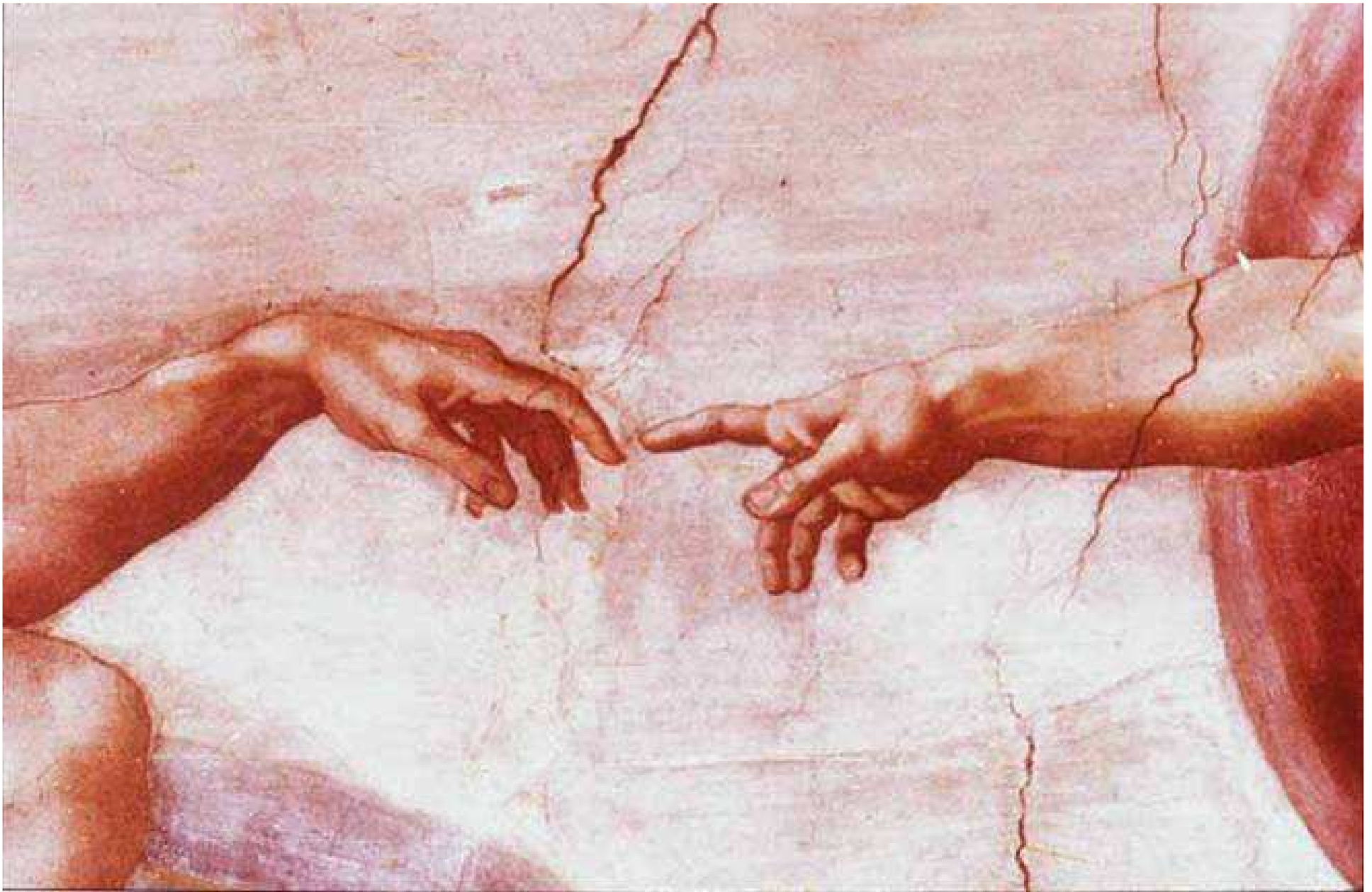
Lap sub-total hysterectomy, Hubertus Hosp. Berlin

today Ergonomics comprises

- physical ergonomics
- cognitive ergonomics
- macro-ergonomics

Areas of physical ergonomics

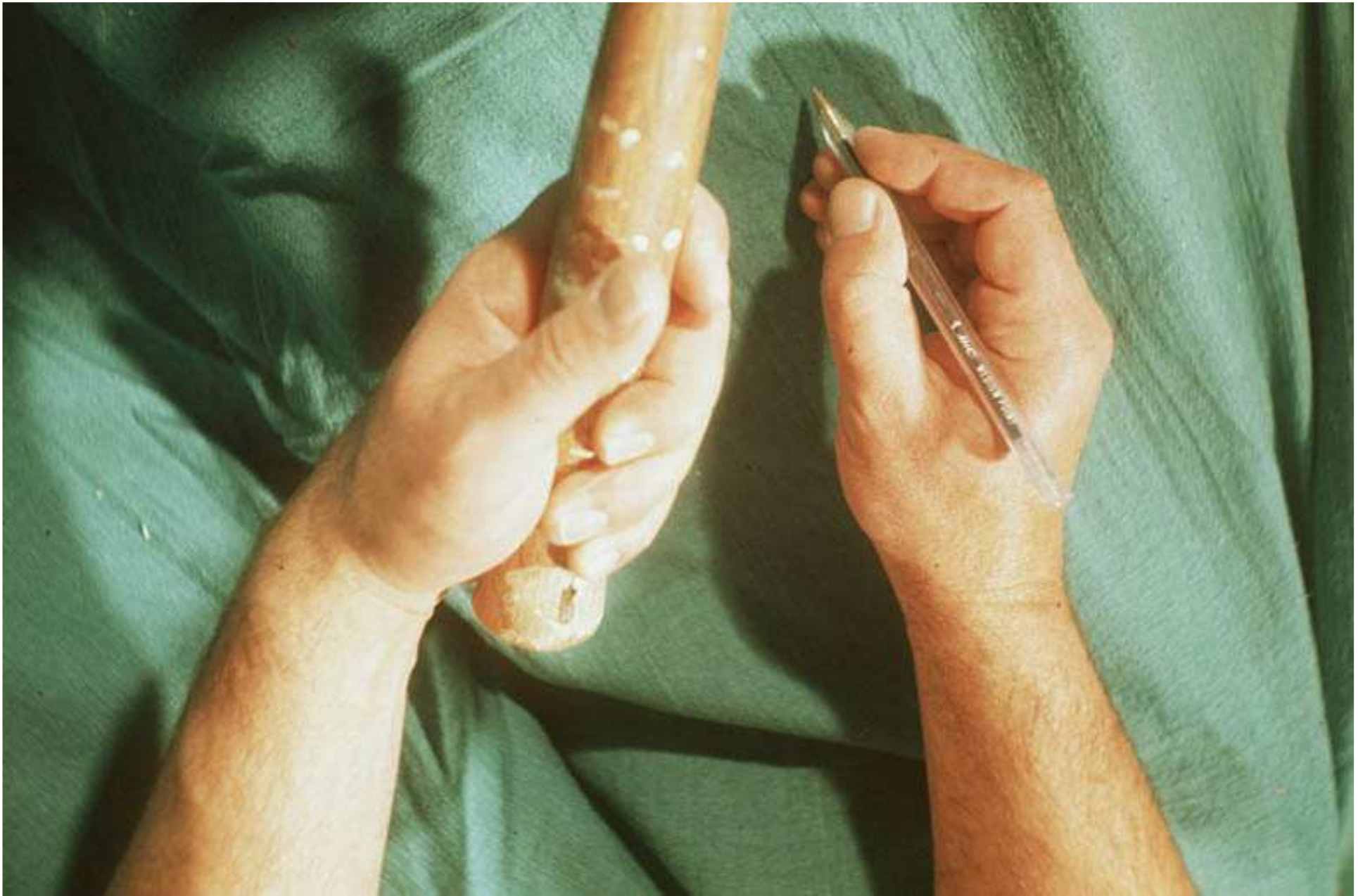
- Equipment design - handles
- Workplace layout – desk, office
- Environmental factors – lighting, noise, temperature, smell etc
- Skill, training, safety



Hand grips and handle design

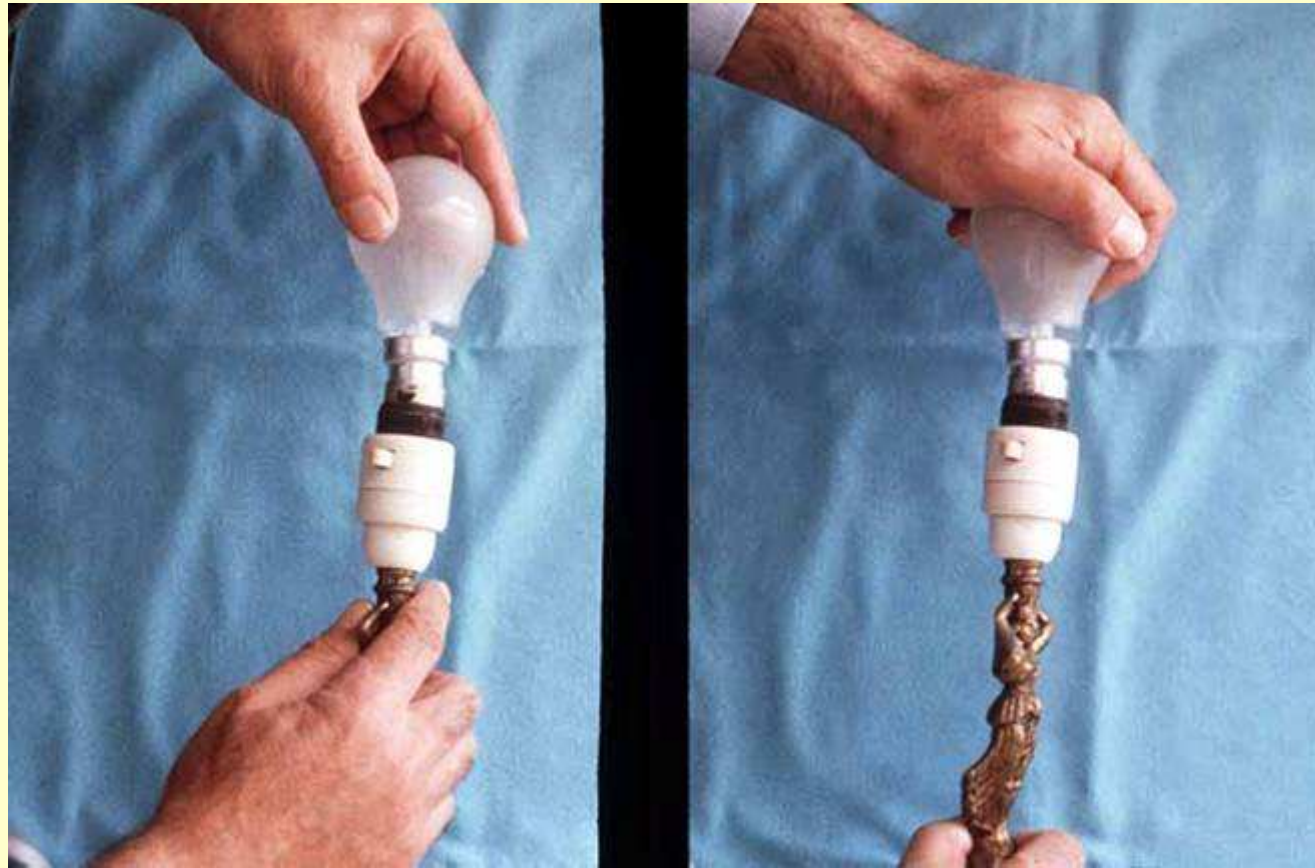
Types of hand grip

- Power grip
- Precision grip
- Double grips
- Variations

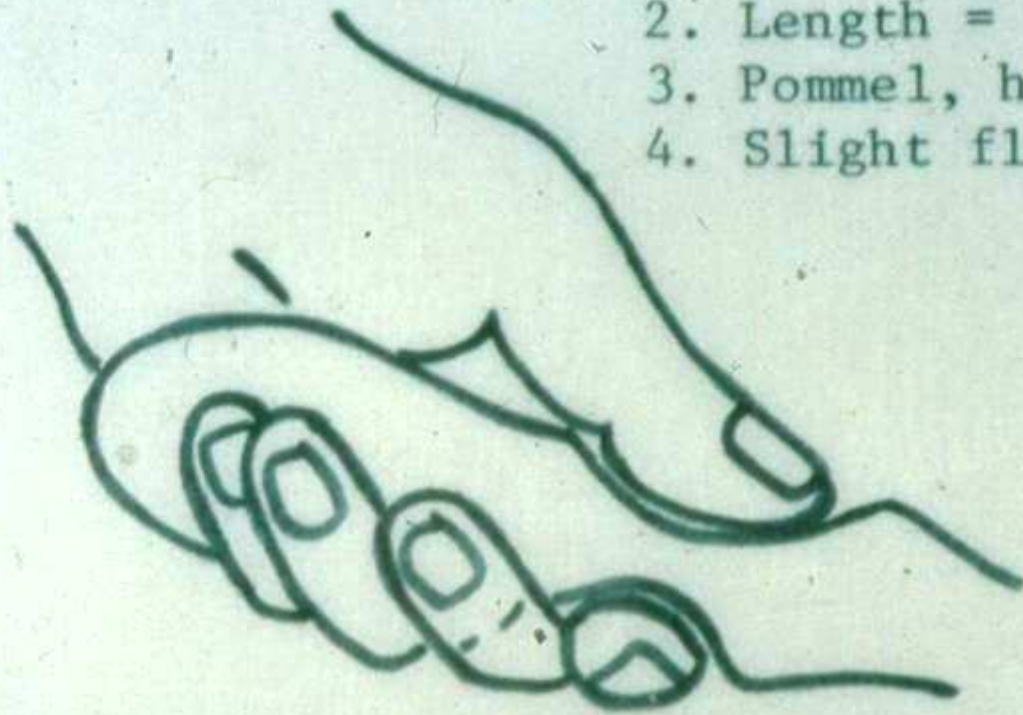


Power grip

precision grip



1. Large contact area
2. Length = palm width
3. Pommel, hilt
4. Slight flattening (rotat

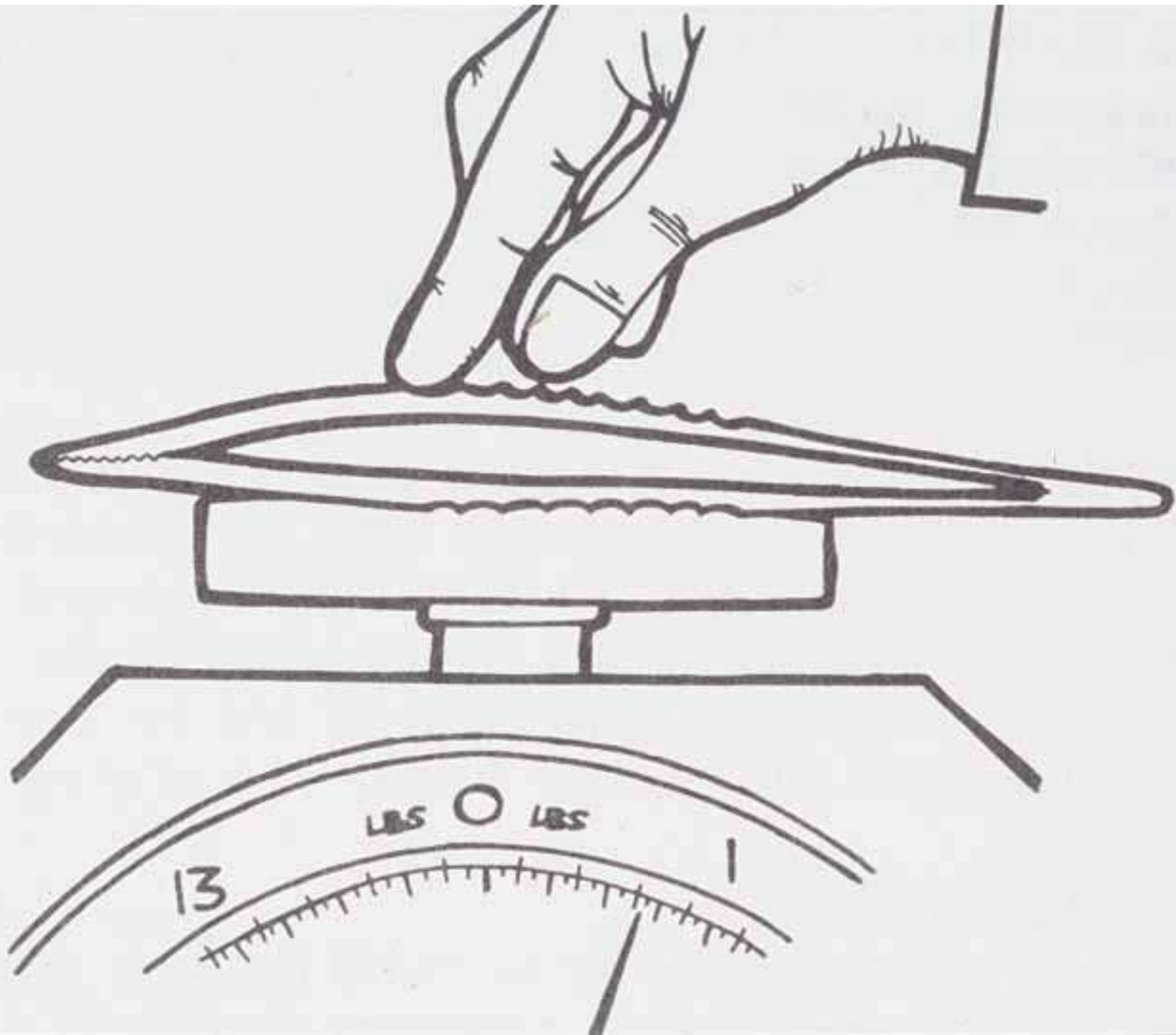


5. Slight hollowing, for thumb, index
6. Angled to shaft, if appropriate
7. Within envelope of reach for limb segment
8. No sharp projections
9. Clearance, including gloves
10. Insulation - heat, vibration, electricity

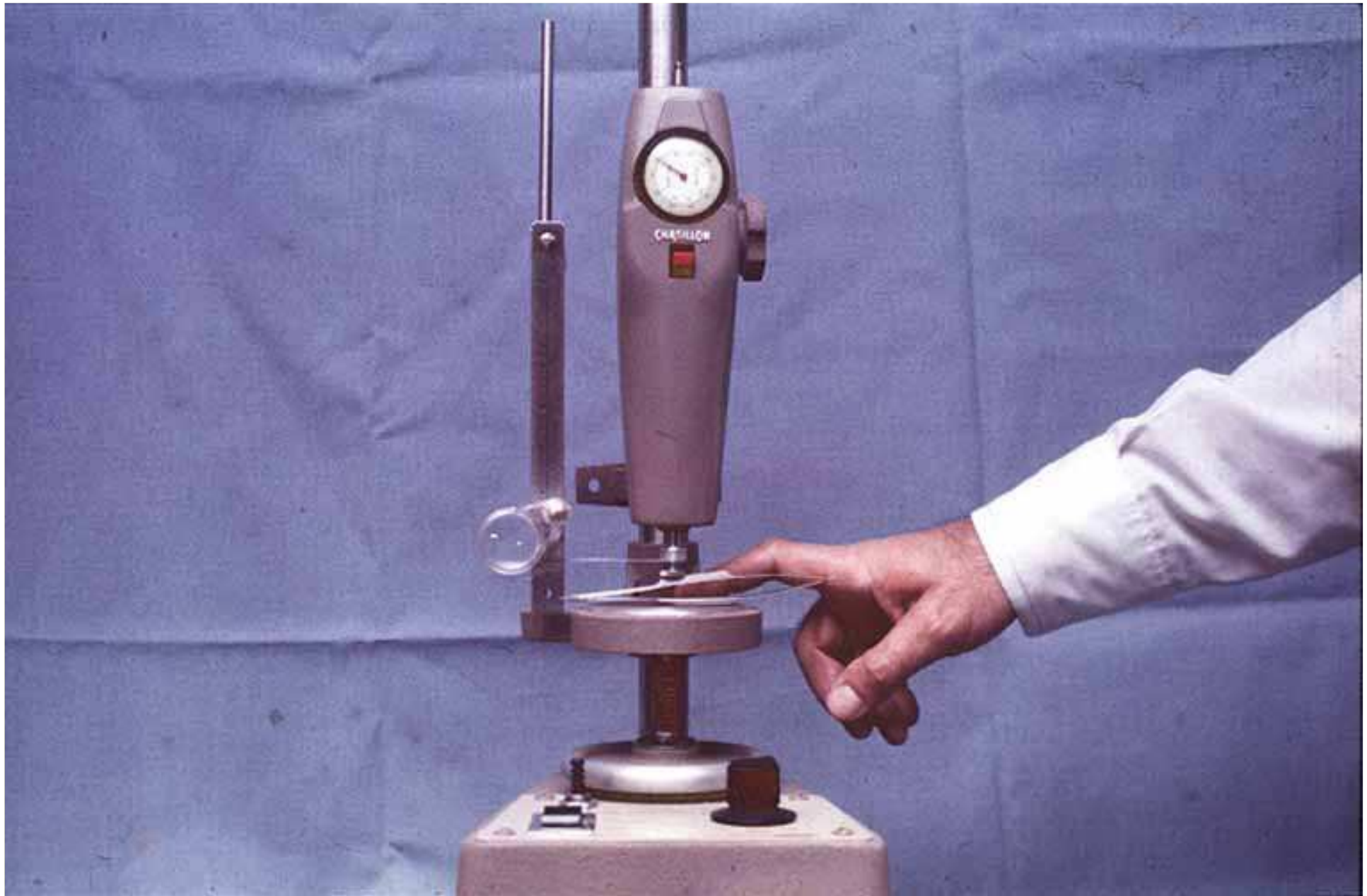


Precision grip criteria for micro needleholder design

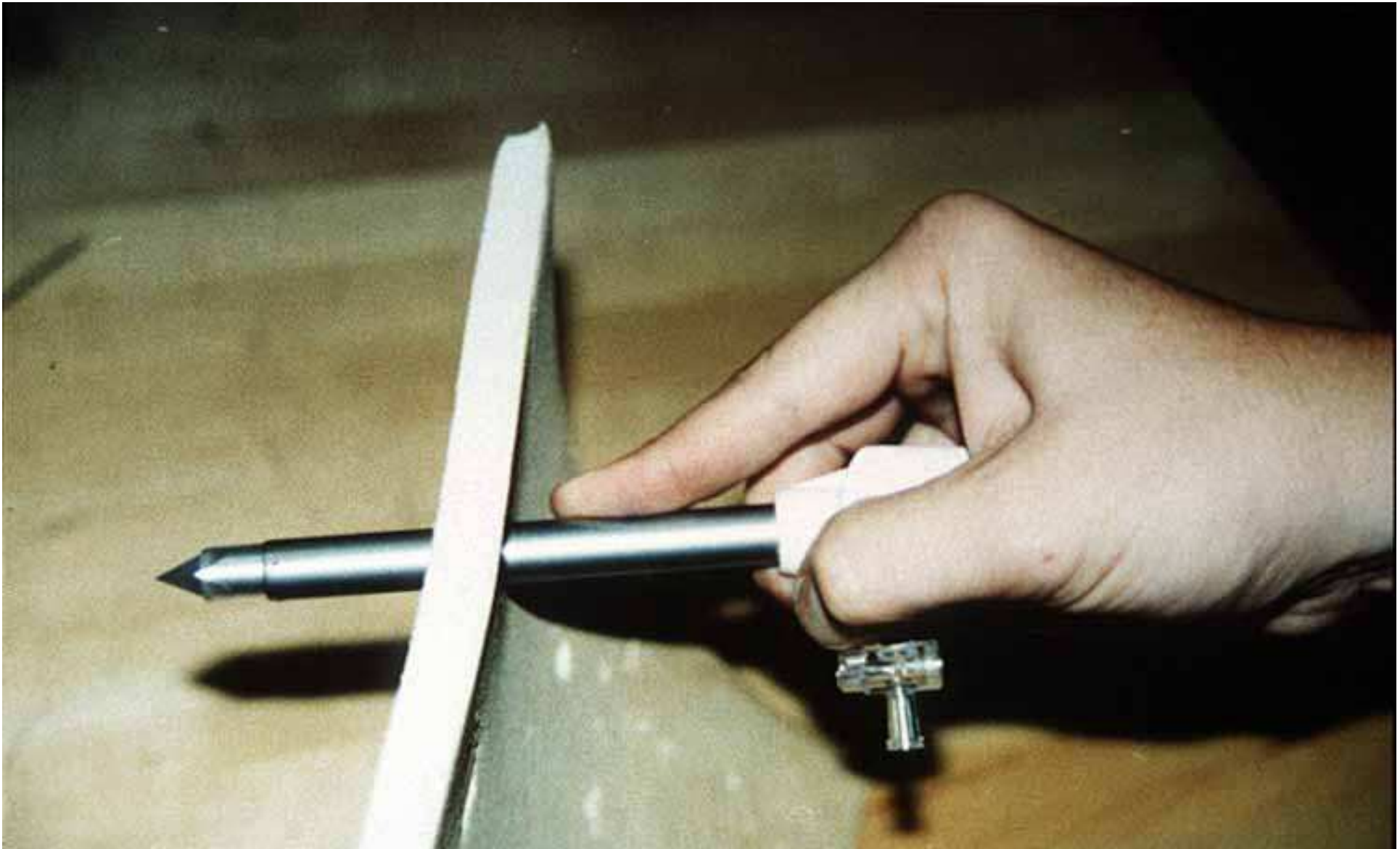
- length - 10 cm from fingertips to thumb cleft
- crosssection - circular
- thickness - 1 cm within fingertips
- stiffness - 50 to 80 gm weight (0.5 - 0.8 N)



- Stiffness of dissecting forceps

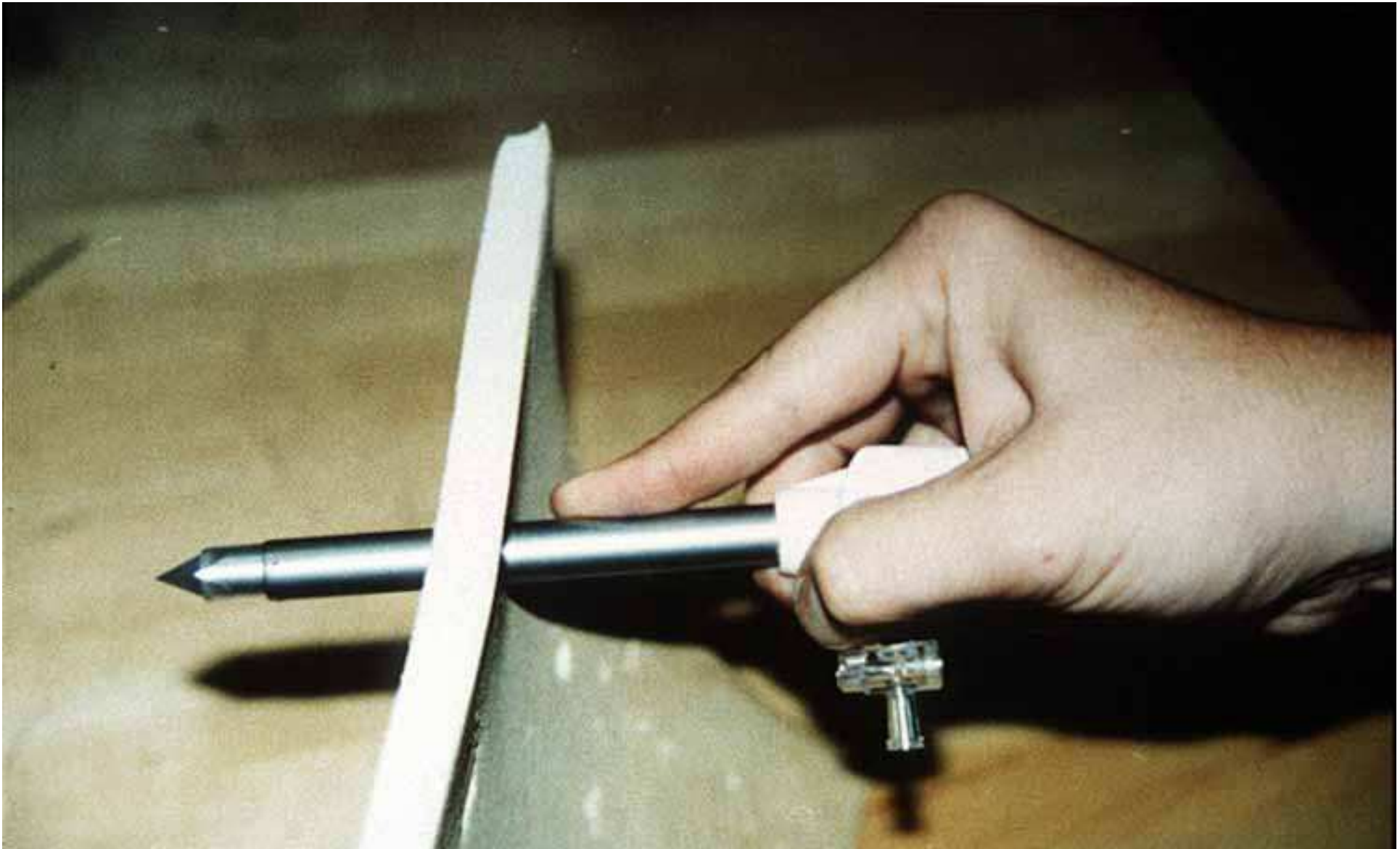


Measuring stiffness of microsurgical needleholder

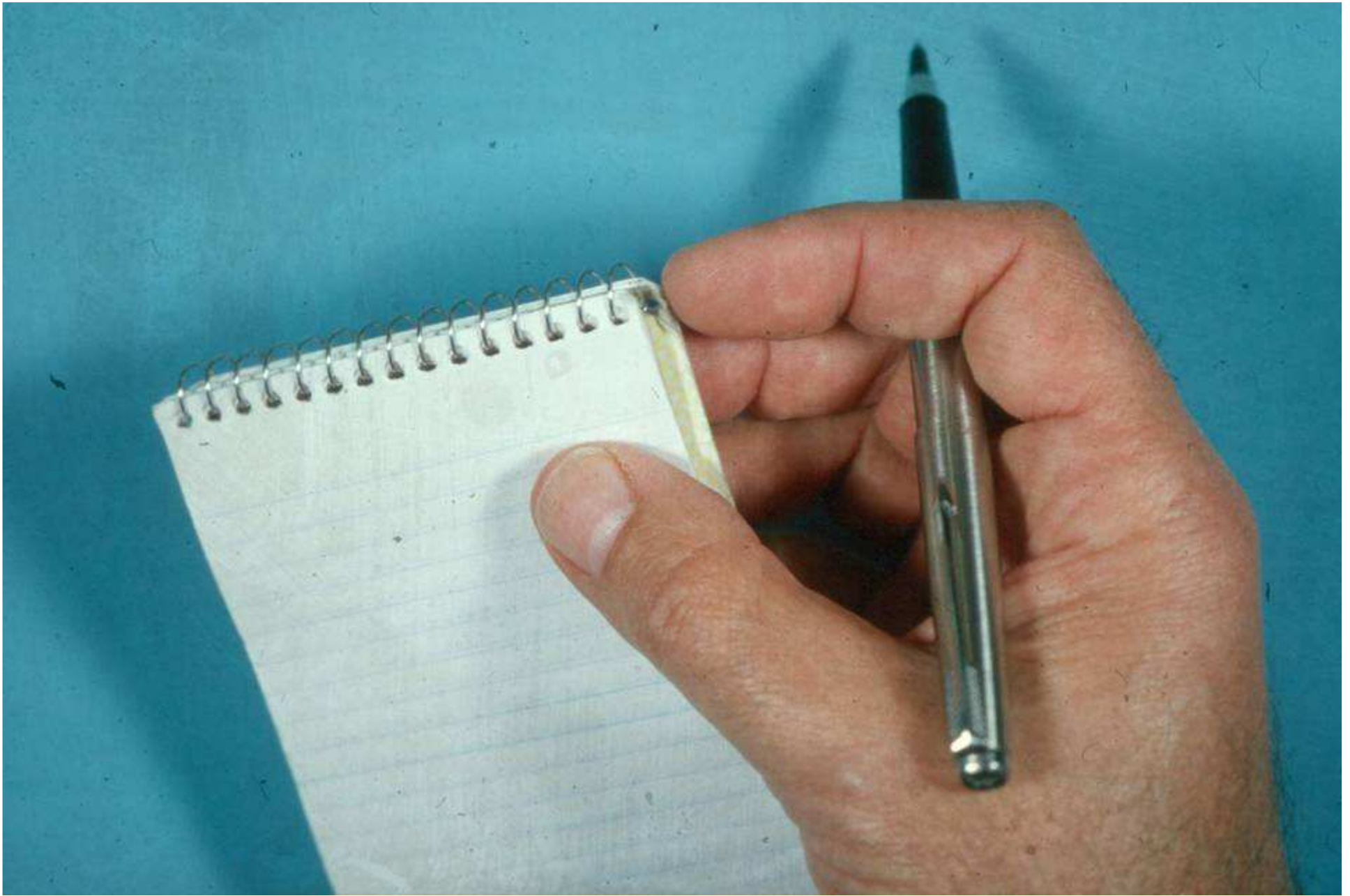


> 20 deaths from lap trochar injuries in U.S.A.
in 1992 - why ?





Why ? Tense grip - distortion - failure of safety shield



THE HAND HAS TWO GRIPS An Aspect of Surgical Dexterity

MICHAEL PATKIN

M.B. Melb., F.R.C.S., F.R.C.S.E.

LATE SURGICAL REGISTRAR, NORTH MIDDLESEX HOSPITAL, LONDON, N. 18 *

EVERY table tennis-player knows that the hand can control two balls comfortably (fig. 1). Similarly, the car driver can control both the steering-wheel and a cigarette placed between index and middle fingers. Surgeons also use their hands for multiple functions at the same time; but little attention has been paid to this, since descriptions of operative technique usually concentrate on the tissues and instruments.

STORING INSTRUMENTS

A pair of dissectors can readily be stored out of the way with the ring and little fingers securing the instrument against the palm. This leaves the thumb, index, and middle fingers free to tie a knot (fig. 2). This technique is used for interrupted sutures: it saves putting down the dissectors (often out of the field of vision) and picking them up again.

In terms of conventional time-and-motion studies,¹ a number of "Therbligs" or basic elements of motion have been eliminated. As applied to the

transport empty again, search, grasp, transport loaded, secure tissue for next suture.

The saving in time lies not in the increase of speed in each motion, but in eliminating unnecessary movements. There is the disadvantage of learning a new technique, but the time and effort taken are very little compared with the permanent improvement in operation.

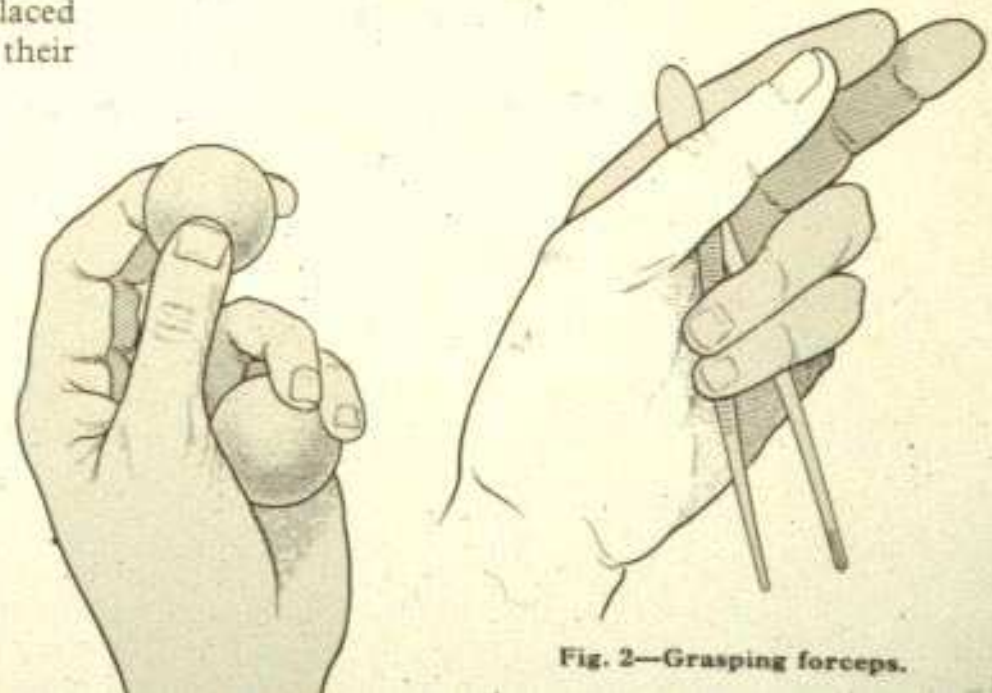
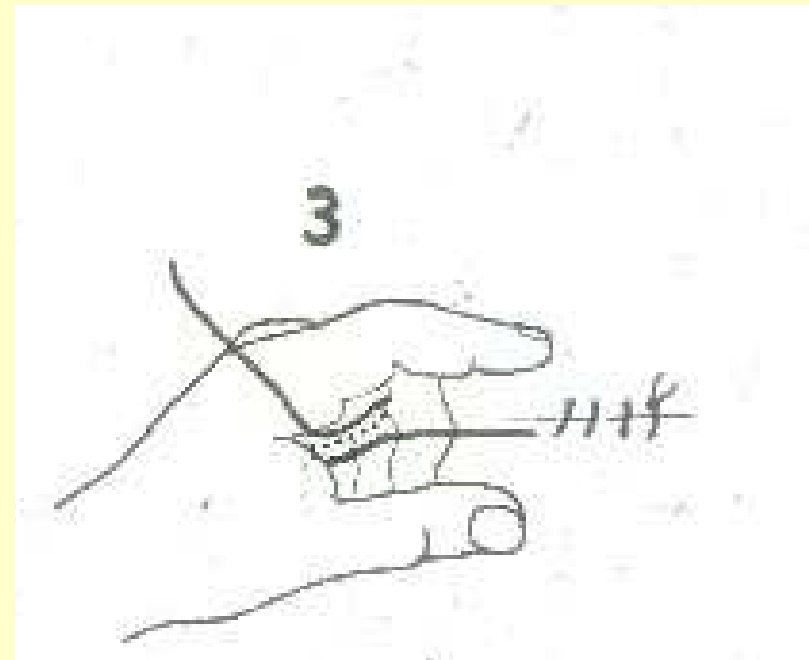
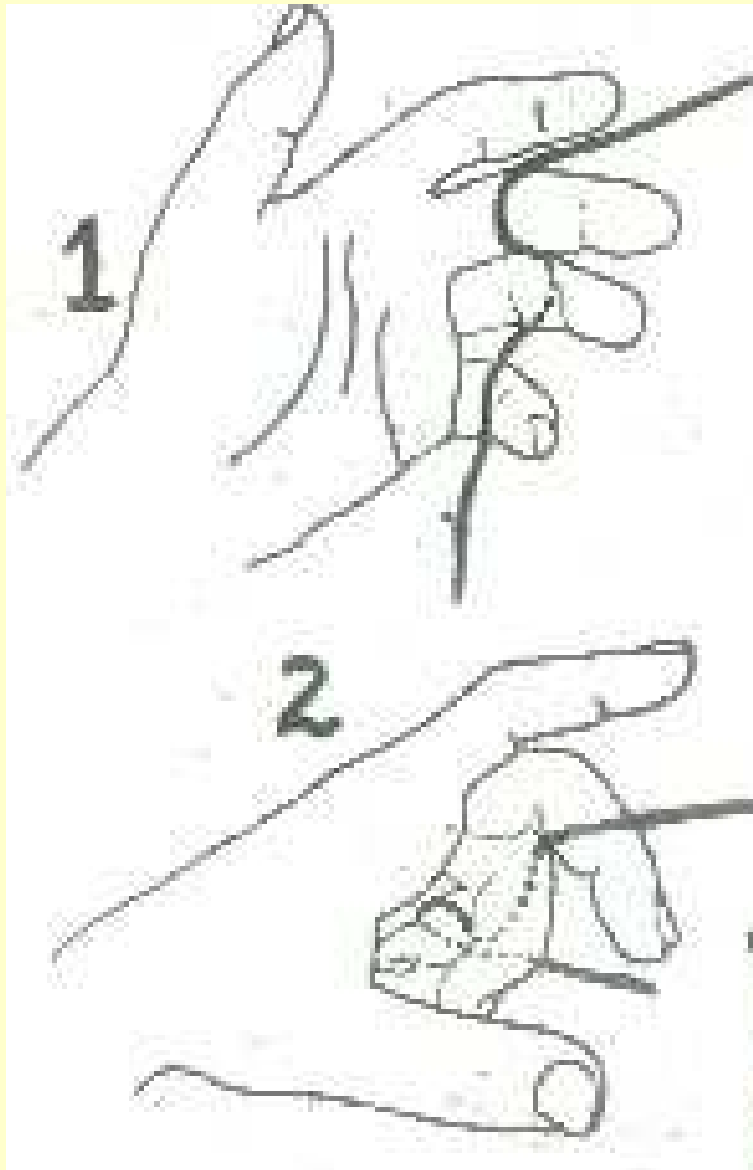


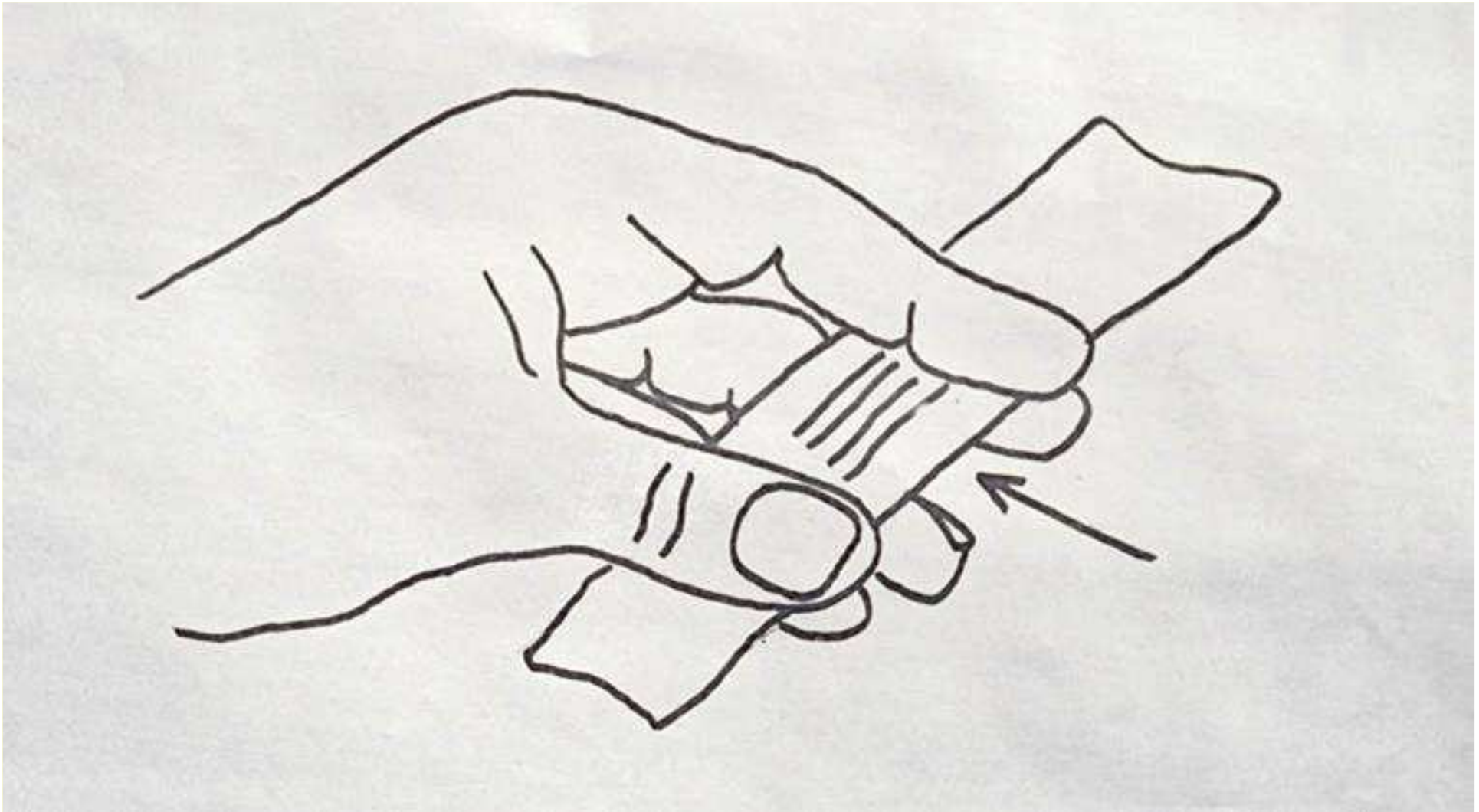
Fig. 2—Grasping forceps.

- Double grips of the hand

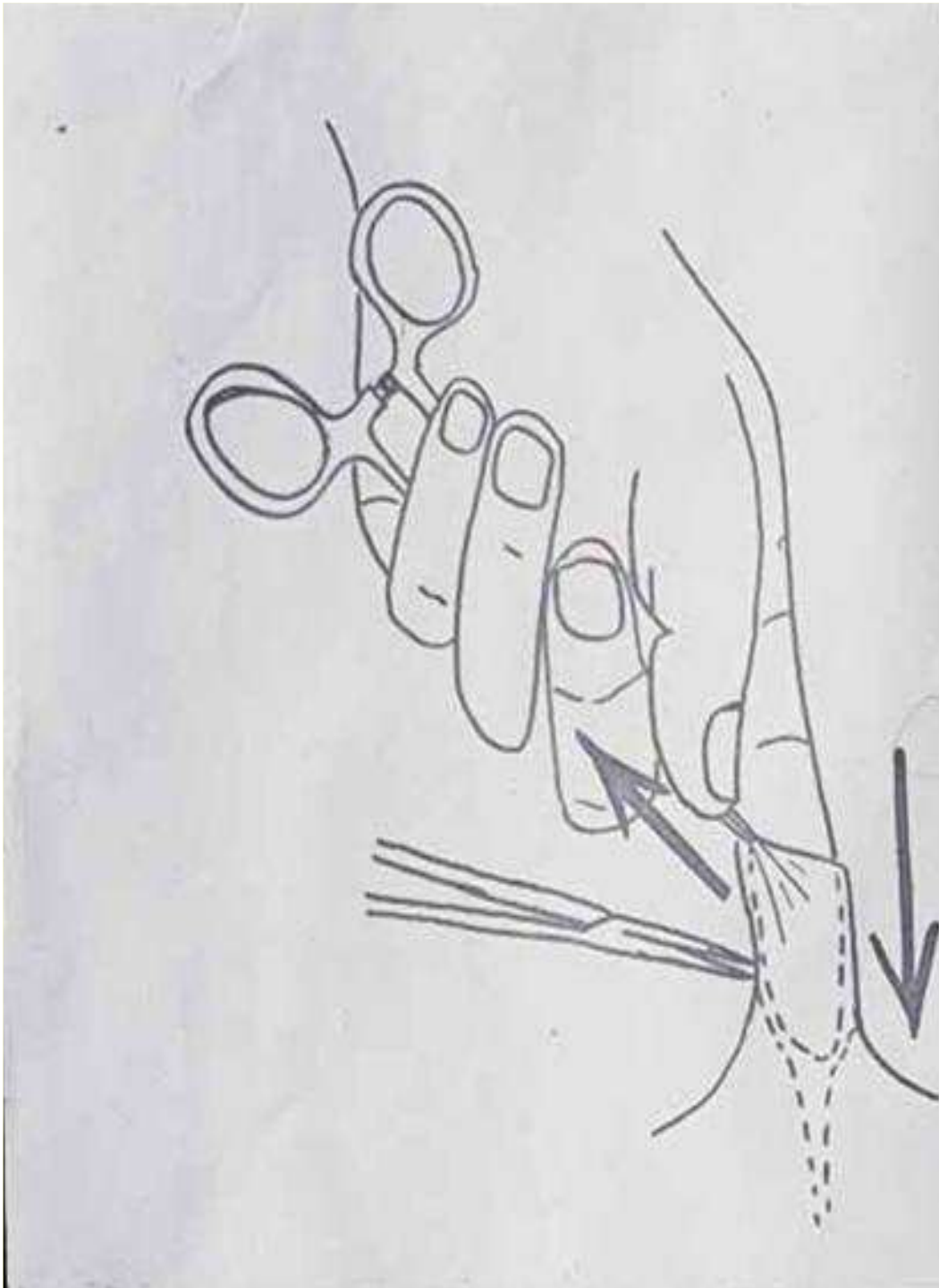


Suture storage grip





- Double grip, stretch
- Incision at right angle to line of tension



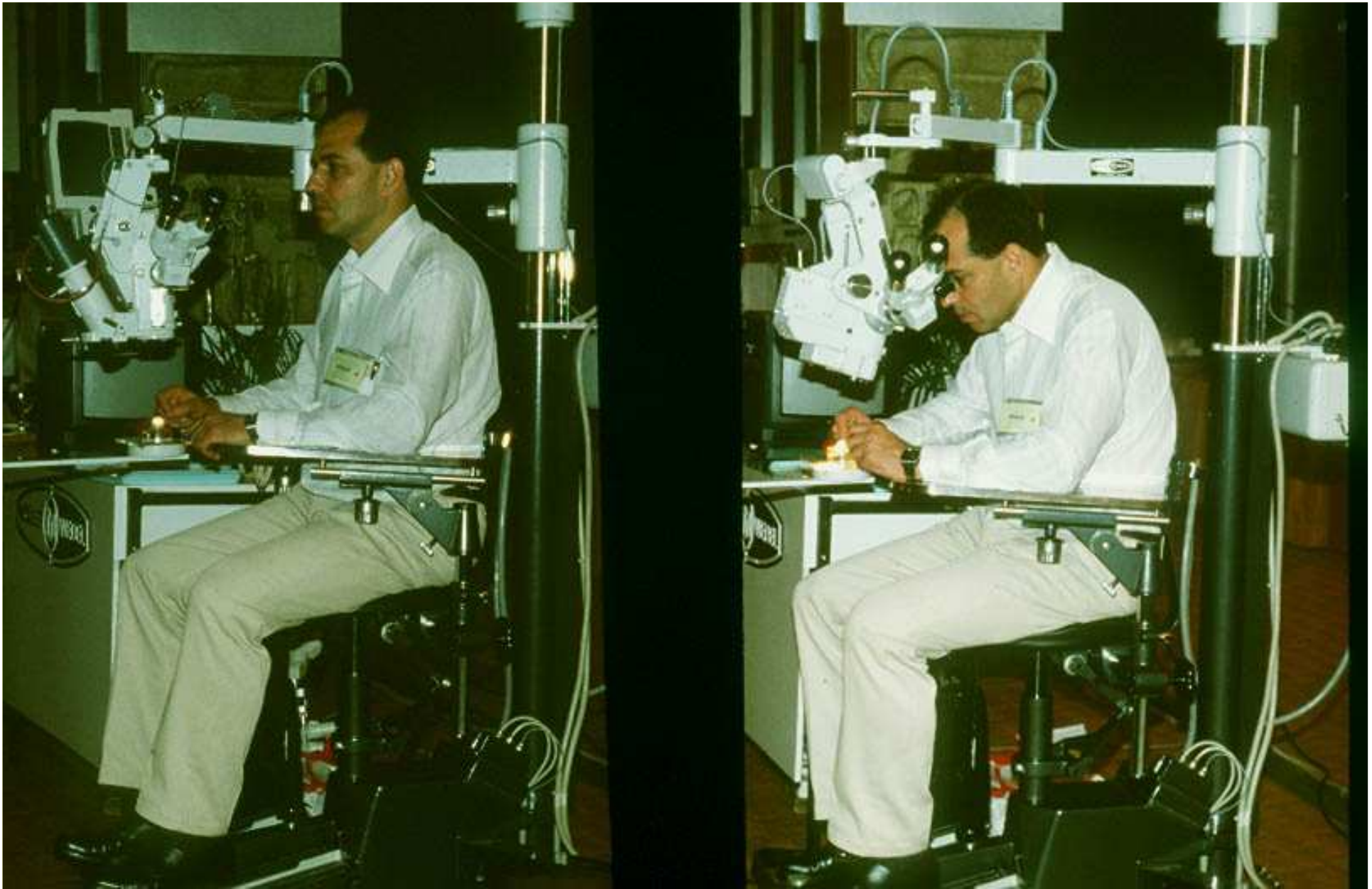
Double hand function

(traction on hollow structure with fingertip inside)

e.g.

- adherent hernial sac
- scarred duodenal stump
- horrible gall-bladder

seating



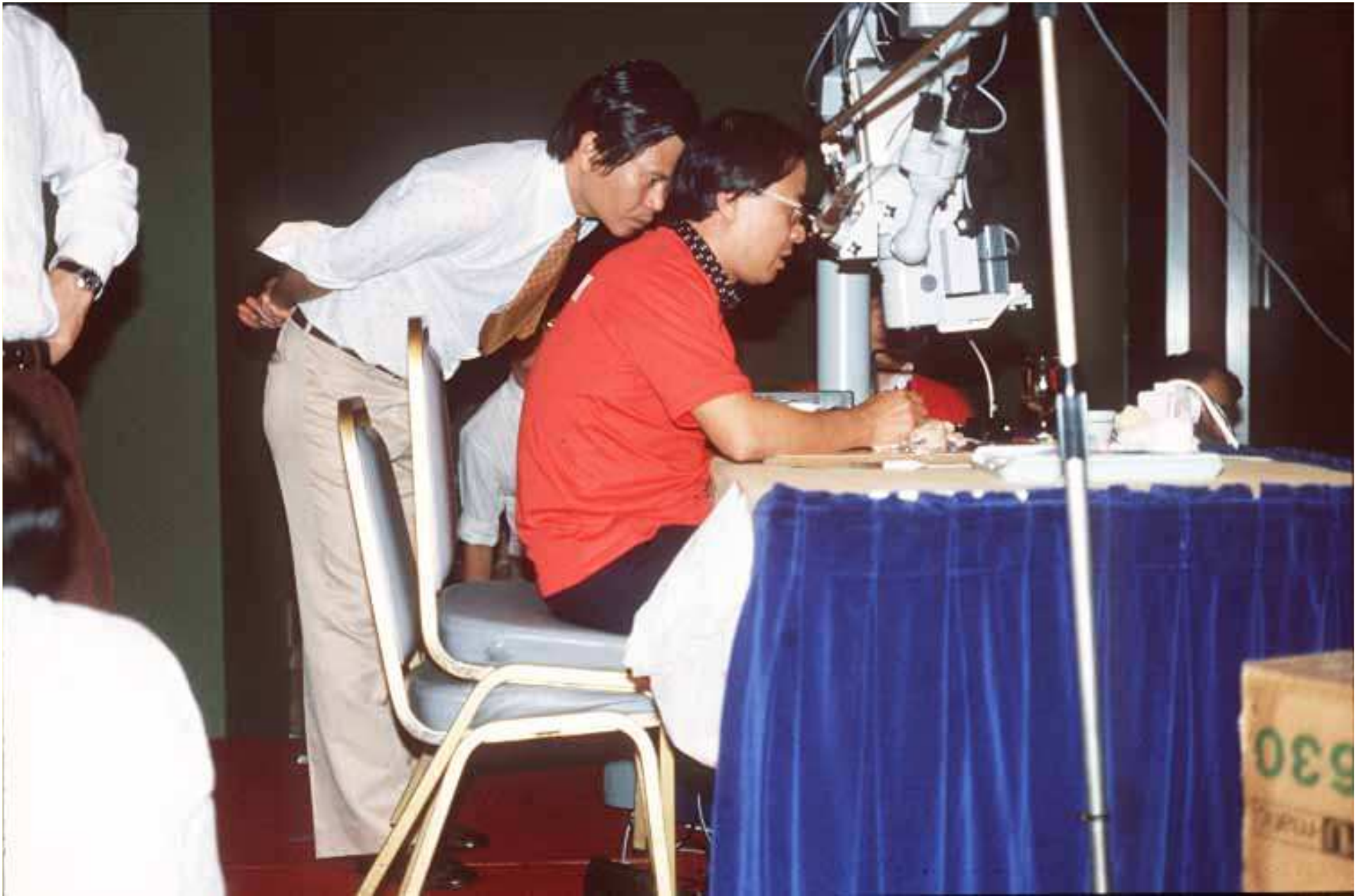
Zeiss microscope at Singapore 1977



- 20 cm ocular extension needed



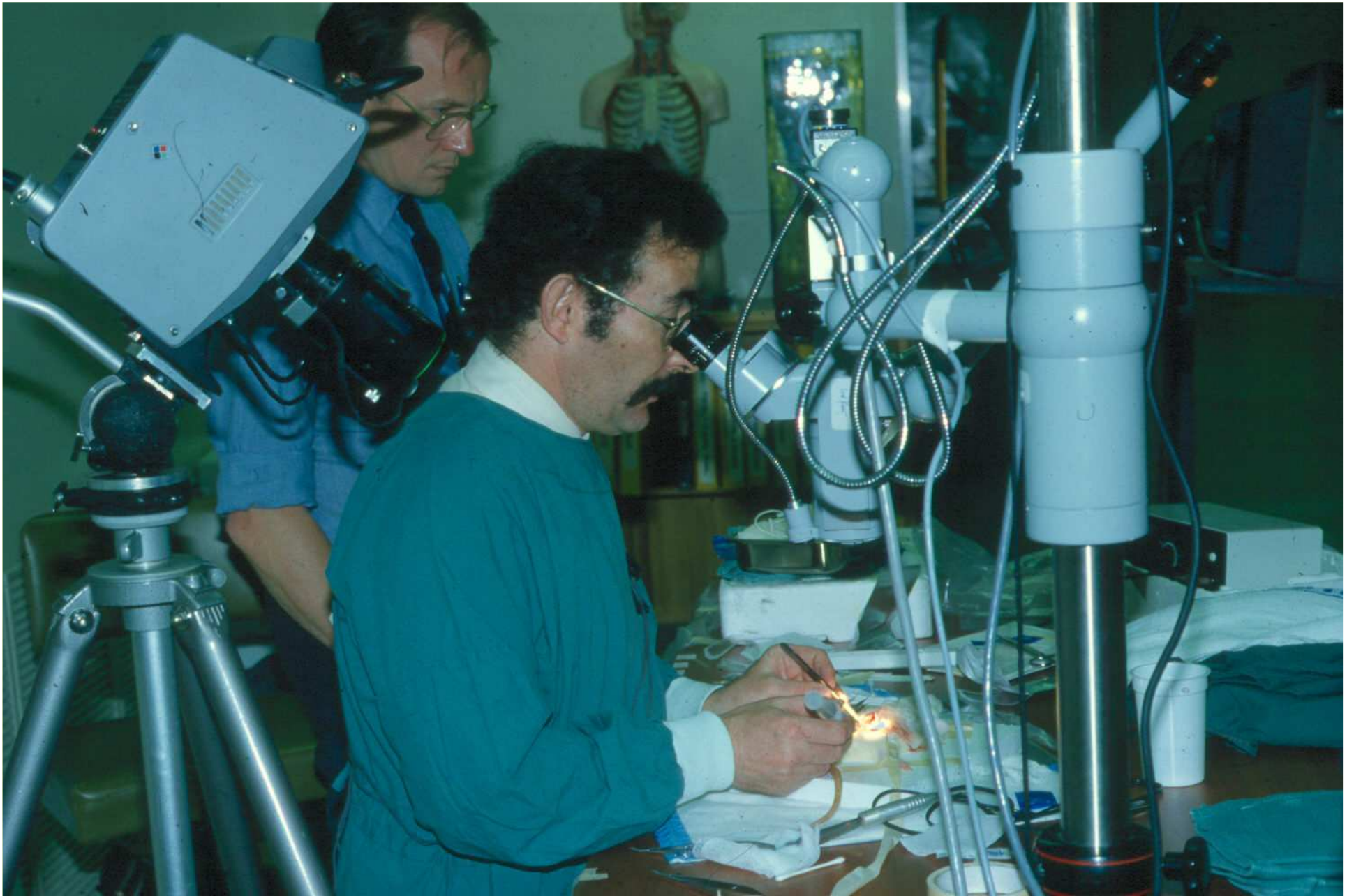
Pioneer microsurgeon needs back-brace



Prof. Harii at Singapore 1978





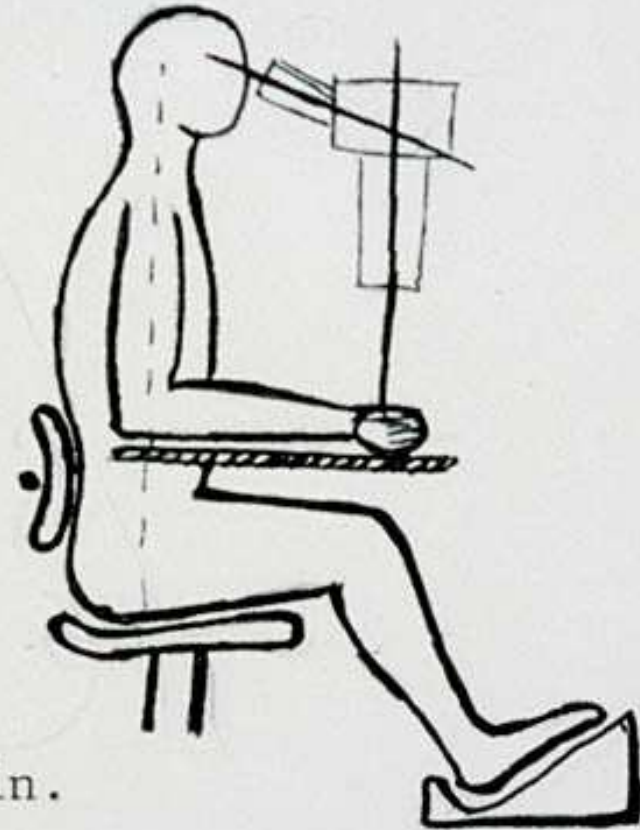


Robert Winston at gynae micro workshop, Adelaide 1981



POSTURAL NEEDS IN MICROSURGERY

1. Hand support
2. Forearm horizontal
3. Arm by side, elbow in
4. Trunk & head vertical
5. Gaze 15-45° downwards
6. Objective over fingertips
7. Focal length to tissue plane
8. Seat height, area, slope, edge, give.
9. Lumbar support
10. Leg clearance
11. Foot support, pedal design
12. ...alter exposure, start again.



10 years before office ergonomics

Lap surgery is tiring - be ergonomic

Neck flexed

Arm by side,
support if
available

Relaxed
hand-grip



Subdued lighting from
side or above

Monitor 15-30° below
horizontal and close

Port sites for neutral wrist
posture, hands at elbow
height

Operating table at pubis height
for non-obese patient

Platform for shorter
operator or assistant

www.mpatkin.org

060901

Lap surgery is tiring - be ergonomic

Neck flexed

Arm by side,
support if
available

Relaxed
hand-grip



Subdued lighting from
side or above

Monitor 15-30° below
horizontal and close

Port sites for neutral wrist
posture, hands at elbow
height

Operating table at pubis height
for non-obese patient

Platform for shorter
operator or assistant

www.mpatkin.org

060901

Lap surgery is tiring - be ergonomic

Neck flexed

Arm by side,
support if
available

Relaxed
hand-grip



Subdued lighting from
side or above

Monitor 15-30° below
horizontal and close

Port sites for neutral wrist
posture, hands at elbow
height

Operating table at pubis height
for non-obese patient

Platform for shorter
operator or assistant

www.mpatkin.org

060901

Lap surgery is tiring - be ergonomic

Neck flexed

Arm by side,
support if
available

Relaxed
hand-grip



Subdued lighting from
side or above

Monitor 15-30° below
horizontal and close

Port sites for neutral wrist
posture, hands at elbow
height

Operating table at pubis height
for non-obese patient

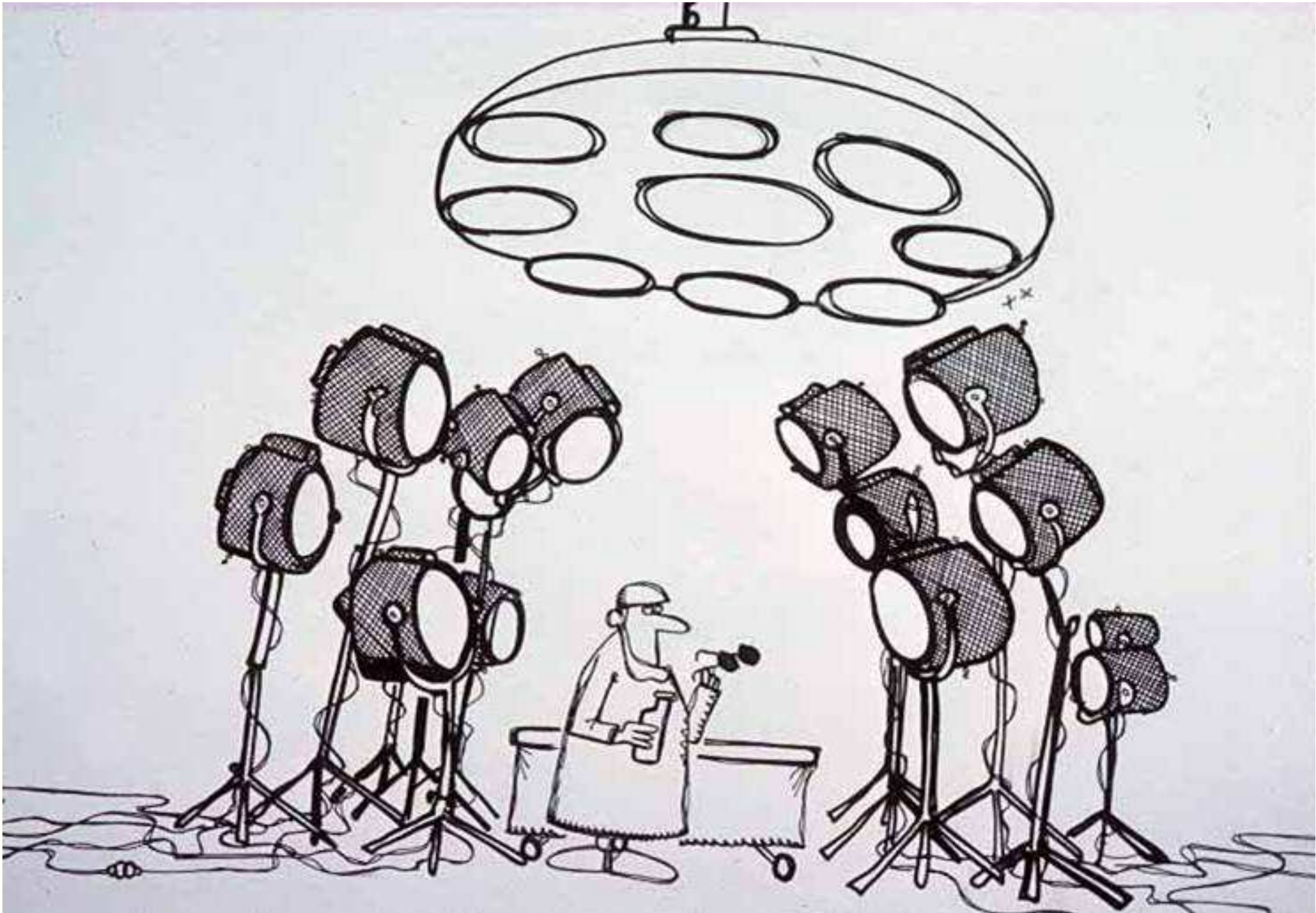
Platform for shorter
operator or assistant

www.mpatkin.org

060901

environmental factors

- Lighting, visual factors
- Temperature, humidity
- Noise etc etc



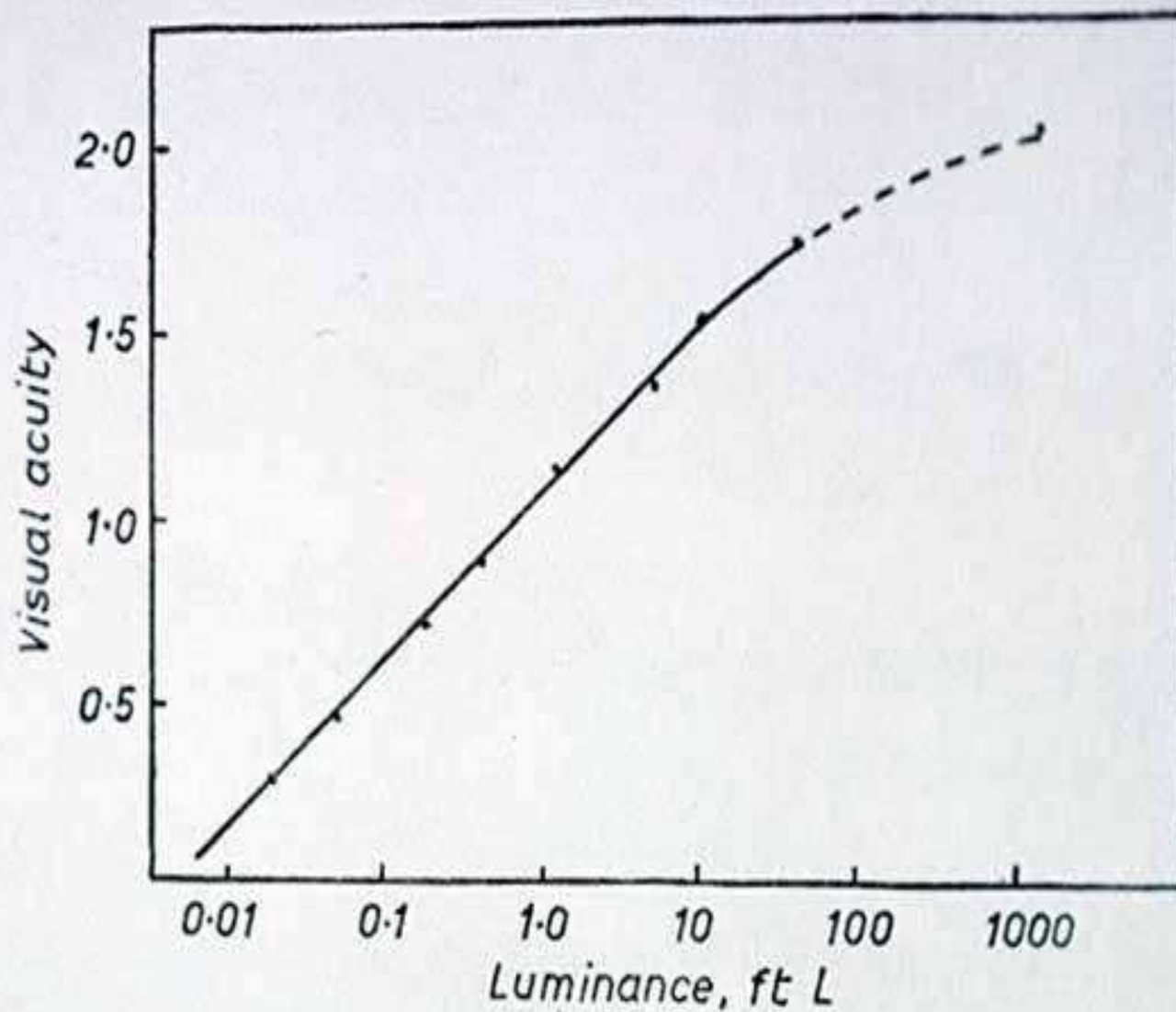


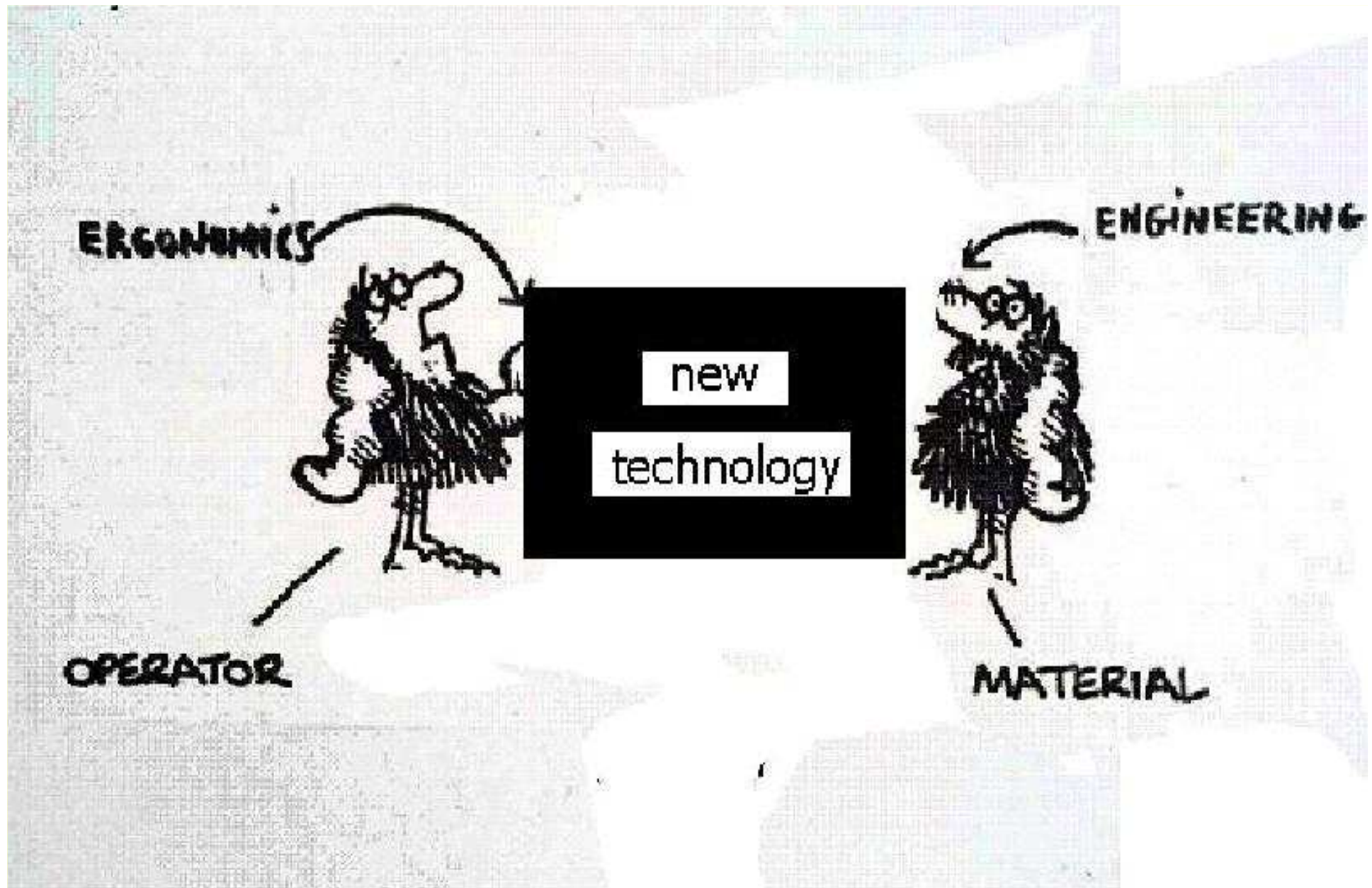
Fig. 100. The relationship between visual acuity and luminance (after Lythgoe, 1932).

Ergonomics in surgery - 3 phases

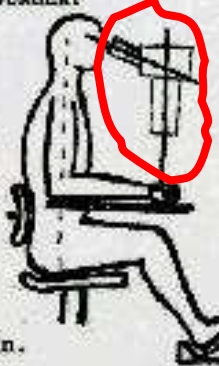
Ergonomics in surgery - 3 phases

- *pre-modern - 1846 anaesthesia*
- *modern*
- *post-modern*
 - micro 1970s*
 - lap 1990s*
 - robotic 2000s*

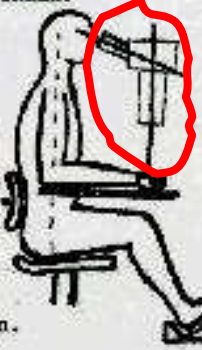

Unaided normal human capacity is
no longer adequate



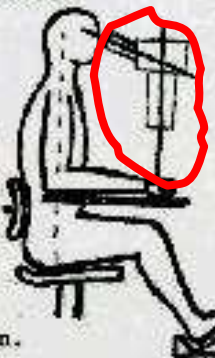
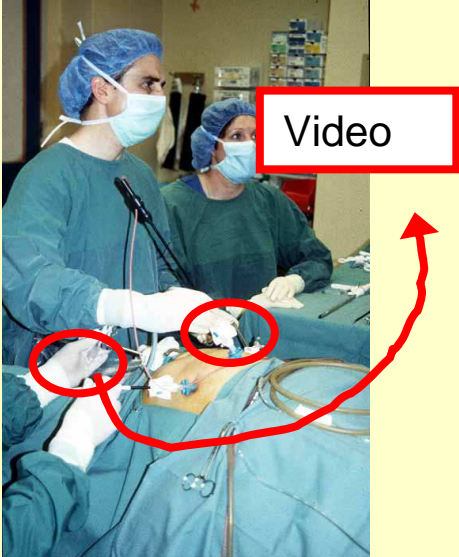
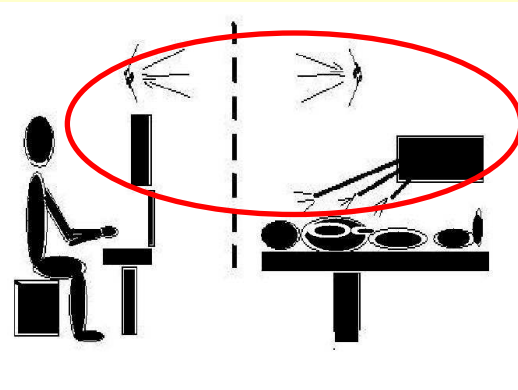
The extra layer of technology

micro	lap	robotic
<p style="text-align: center;">POSTURAL NEEDS IN MICROSURGERY</p> <ol style="list-style-type: none"> 1. Hand support 2. Forearm horizontal 3. Arm by side, elbow in 4. Trunk & head vertical 5. Gaze 15-45° downwards 6. Objective over fingertips 7. Focal length to tissue plane 8. Seat height, area, slope, edge, give. 9. Lumbar support 10. Leg clearance 11. Foot support, pedal design 12. ...alter exposure, start again. 		
<ul style="list-style-type: none"> • Microscope • V fine instruments 		

The extra layer of technology

micro	lap	robotic
<p>POSTURAL NEEDS IN MICROSURGERY</p> <ol style="list-style-type: none"> 1. Hand support 2. Forearm horizontal 3. Arm by side, elbow in 4. Trunk & head vertical 5. Gaze 15-45° downwards 6. Objective over fingertips 7. Focal length to tissue plane 8. Seat height, area, slope, edge, give. 9. Lumbar support 10. Leg clearance <ol style="list-style-type: none"> 1. Foot support, pedal design 2. ...alter exposure, start again. 		
<ul style="list-style-type: none"> • Microscope • V. fine instruments 	<ul style="list-style-type: none"> • Long instruments + friction • Video system 	

The extra layer of technology

micro	lap	robotic
<p>POSTURAL NEEDS IN MICROSURGERY</p> <ol style="list-style-type: none"> 1. Hand support 2. Forearm horizontal 3. Arm by side, elbow in 4. Trunk & head vertical 5. Gaze 15-45° downwards 6. Objective over fingertips 7. Focal length to tissue plane 8. Seat height, area, slope, edge, give. 9. Lumbar support 10. Leg clearance <ol style="list-style-type: none"> 1. Foot support, pedal design 2. ...alter exposure, start again. 		
<ul style="list-style-type: none"> • Microscope • V fine instruments 	<ul style="list-style-type: none"> • Long instruments + friction • Video system 	<ul style="list-style-type: none"> • Mechatronics • Video system

Ergonomic factors in micro-surgery

- *[hand tremor]*
- *[instrument design]*
- *[visual factors]*
- **seating**

Ergonomics in lap surgery

Ergonomics in lap surgery

- 2-D view of 3D space

Ergonomics in lap surgery

- 2-D view of 3D space
- eye-hand coordination

Ergonomics in lap surgery

- 2-D view of 3D space
- eye-hand coordination
- limited degrees of freedom

Ergonomics in lap surgery

- 2-D view of 3D space
- eye-hand coordination
- limited degrees of freedom
- instruments not adequate

Cognitive ergonomics in surgery

- Error in hospitals
- Information design

ICU chart

Patient records

Documentation for equipment

etc.

Future applications and research

Video analysis

Heuristics of tissue dissection

Heaps of stuff – Nintendo surgery, intelligent agents



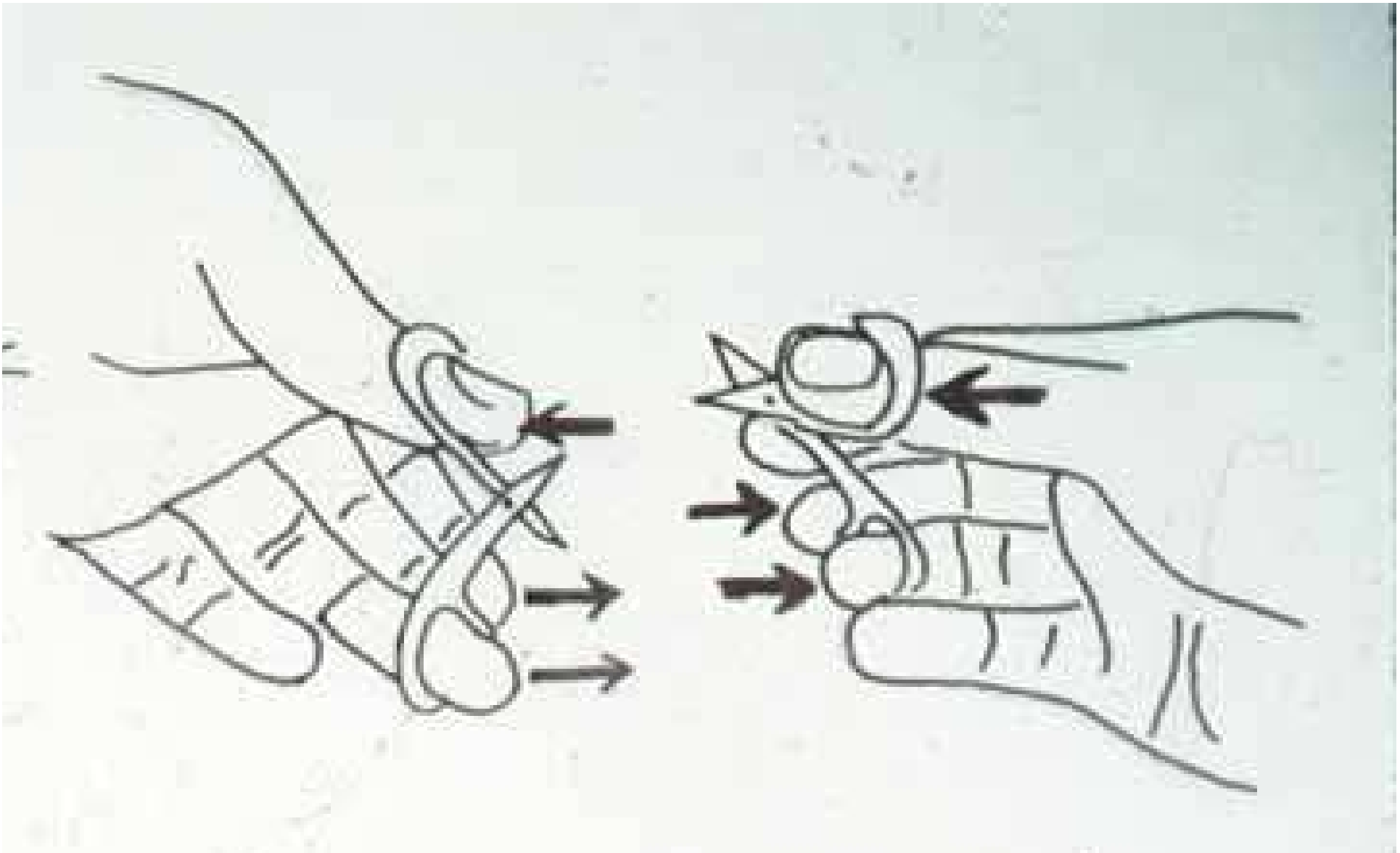








mpatkin.org



Direction of finger and thumb forces for cutting with loose scissors

But first for something completely different

Para-professional skills

- Self-management – fitness, alcohol
- Info mgt, communicating - speaking, ppts,,
- Interpersonal relations - ethics & values
- Technical - drawing, photography, computing
- Forces exerted in surgery
 - AND ... Ergonomics!!